





MOTORISED GEARBOX



QUICK



RACK & PINION MECHANISM



2 WAY CONTROL



150+ PIECES

### **RACK & PINION**





Do - it yourself manual

- Read all instructions carefully before constructing.
- Place all the pieces used in a step on the side before starting.
- (3) Always remove batteries when not in use.

### How to construct



II - CT2 - Use this connector to attach 2 pieces.

III - CT3 - Use this connector to attach 3 pieces.

During assembly ensure position of collar is same as in the image in manual.

### How to dismantle

 Narrow edge to remove connectors

Fit the tool into narrow side of connector collar

# Broad edge to split two pieces

### Safety Guidelines

- 1. Do not mix old and new batteries.
- Do not mix alkaline, standard (Carbon-Zinc) or rechargeable (Nickel-Cadmium) batteries.
- Batteries are to be inserted by matching (+) and (-) polarity markings as shown in the image.
- 4. Non-rechargeable batteries are not to be charged.
- Rechargeable batteries are to be removed before being charged.
- 6. Exhausted batteries are to be removed from toy.
- The supply terminals are not to be short-circuited.
   The kit is not intended for children under 3 years old.
- 9. Remove batteries before cleaning any part of the toy.
- Prevent wire from coming in contact with the wheels and tracks, by using wire clip.



Add 2 x 1.5 V "AA" size batteries

### What is Rack and Pinion?



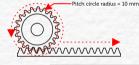
Rack and pinion is a common mechanism used to convert rotational motion into linear motion. This means that this mechanism is suitable if you have an input that creates motion in a circular direction (like and engine or motor), but you want an output where the motion is in a straight line (like a garage door opening up.)

### How does it work:

This mechanism is not that different from the wheels of a car turning and moving the car forward. Similarly, a pinion is a small gear that turns like wheels and creates a linear motion on the rack.

 $A \, rotating \, wheel \, can \, slip, \, but \, a \, rack \, and \, pinion's \, teeth \, mesh \, and \, are \, capable \, of \, transferring \, much \, more \, force.$ 

You might have seen roller coasters using this mechanism to climb slopes. The metal wheels do not have enough friction, and the wheels by themselves would slip. Therefore, they place a rack on the slope and pinion on the car for it to climb.





### How can we calculate speed of rack?

Distance travelled by rack = Circumference of pinion in one rotation

= 2TTr ('r' is pitch circle radius of pinion gear which is 10 mm for this application)

= 2 T x 10 ( T = 3.14)

- EII X 10 (11- 0.11)

= 62.8 mm per rotation of pinion

Distance travelled by rack = 62.8 x R.P.M. of pinion

in one second

= 62.8 x 70 R.P.M.

= 4396 mm per minute

= 4.4 meter per minute (1 meter = 100 centimeter = 1000 millimeter )

= 0.07 meter per second (1 minute = 60 seconds)

## MODEL 1 - FORK LIFT Make 2 sets of this step. STEP - 1 TW1 8 pcs. 4 pcs. CT3 SH 100 2 pcs. CH2 4 pcs. P5 2 pcs. Wheels 4 pcs. STEP - 2 PU5 X 13 1 pc. P7 X 11 1 pc. CH2 4 pcs.

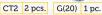








TW1 1 pc.

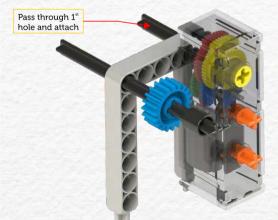




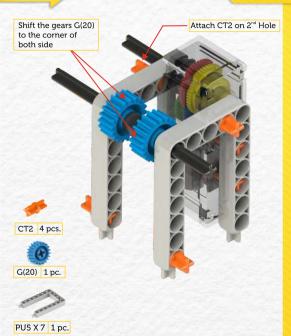
SH 100 1 pc.



Motor With Battery Box 1 pc.





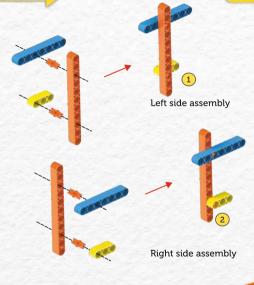




Assembly of step 4 & step 2





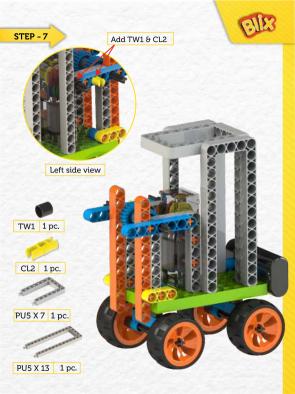












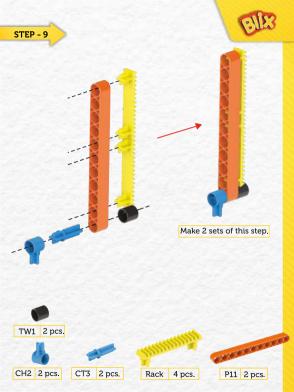


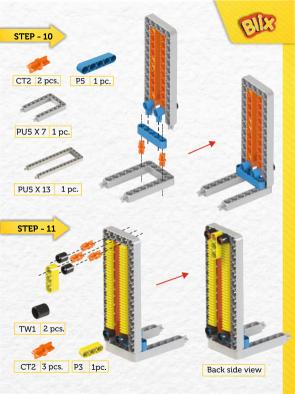




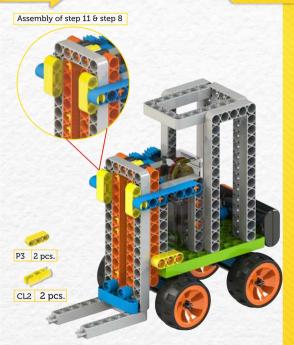


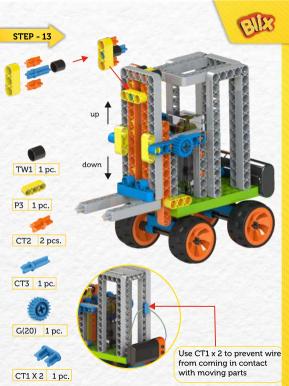
G(20) 2 pcs. G(20) Idler 1 pc.



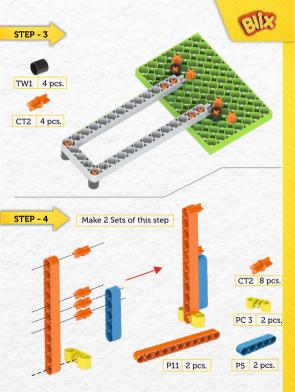


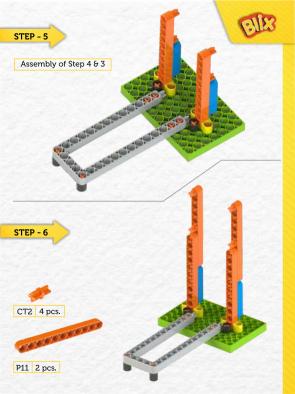


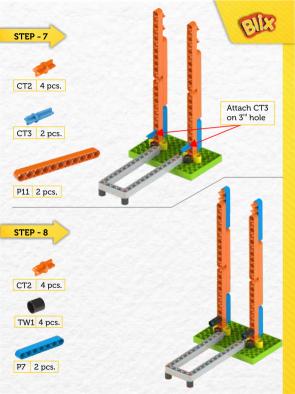




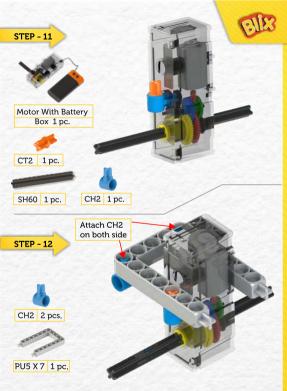


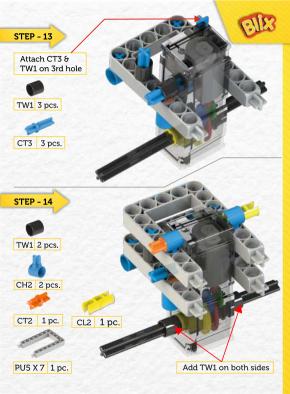






























### Assembly of step 15 & step 10



CT2 4 pcs.









TW1 4 pcs.



Water Co.



Add TW1 on both sides

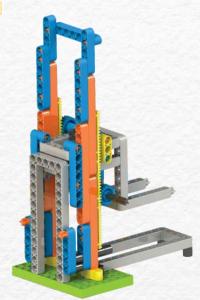




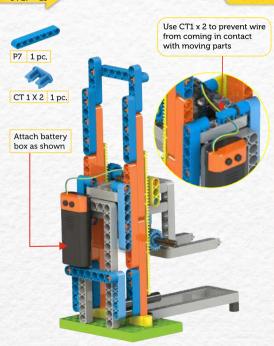
CT2 2 pcs.



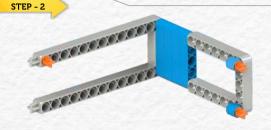
P5 2 pcs.







# MODEL 3 - Vertical Gate STEP - 1 P5 4 pcs. CT3 4 pcs.

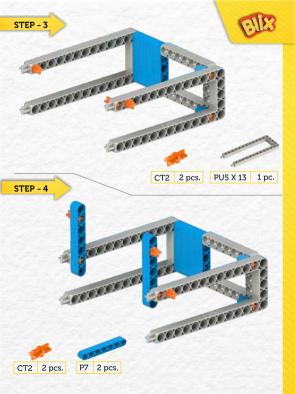


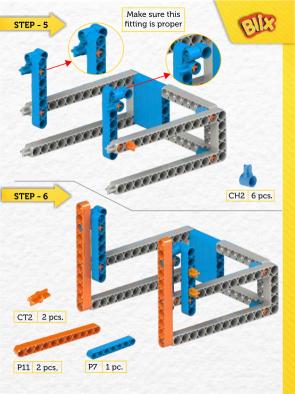


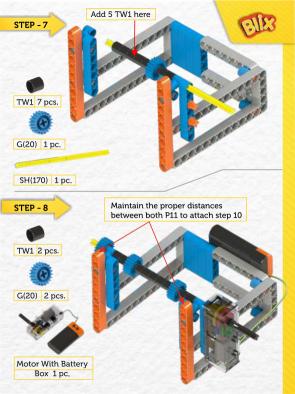


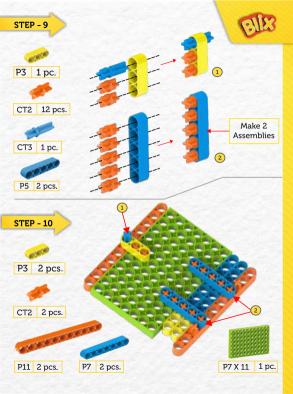


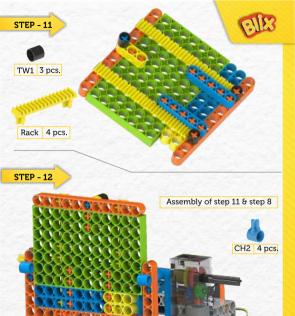








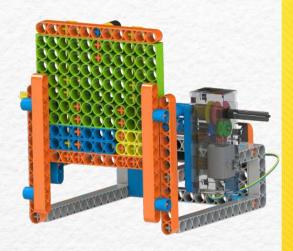






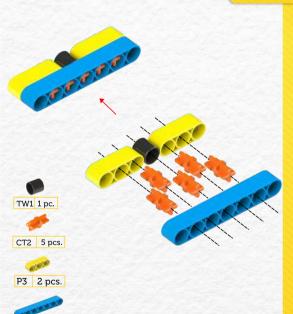




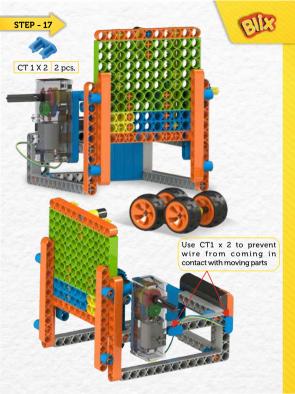


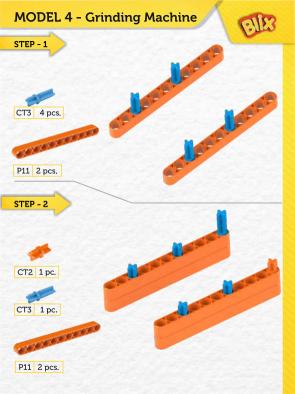
1 pc.



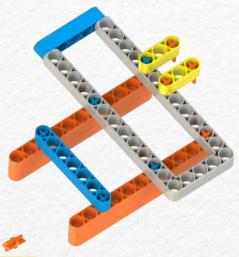












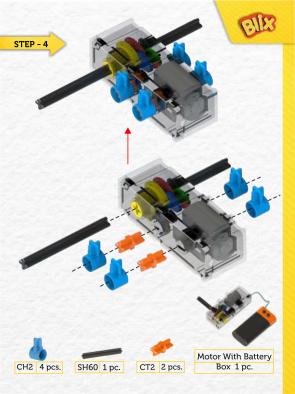


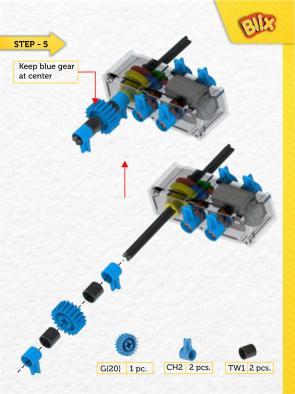






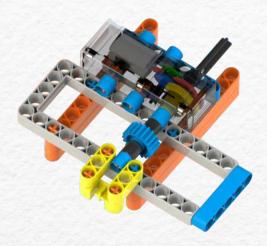




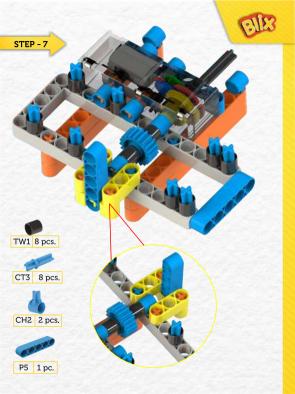




Assembly of step 5 & step 3

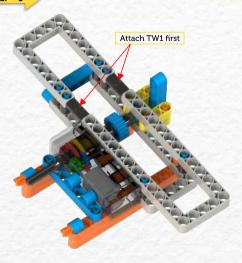




















PU5 X 13 1 pc.





CT2 4 pcs.

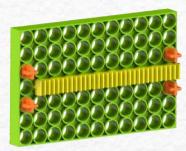


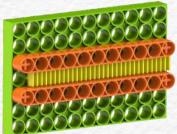
P7 X 11 1 pc.



Rack 2 pcs.

STEP - 10

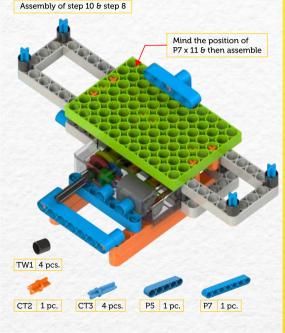




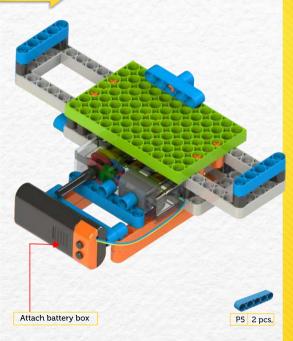


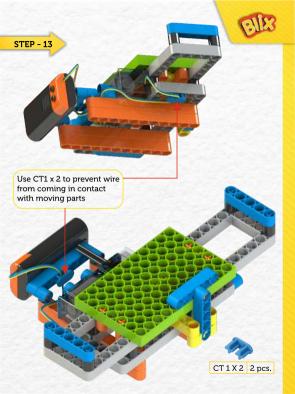
P11 2 pcs.

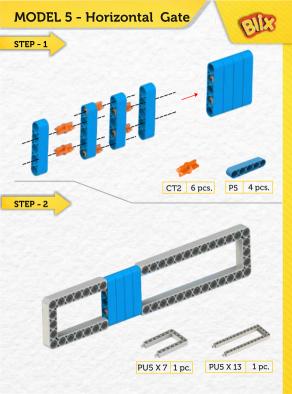


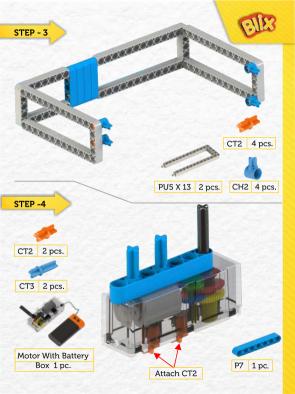
























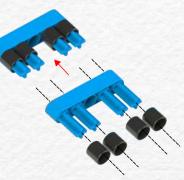




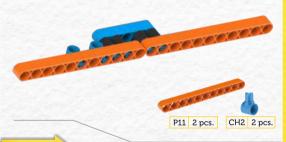
G(20) 1 pc.

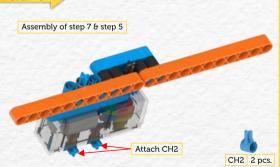
STEP - 6



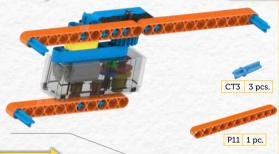


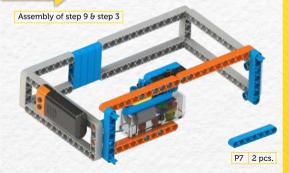


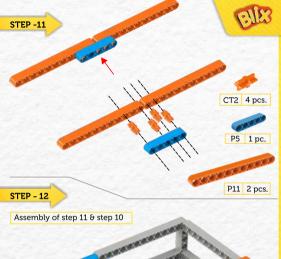


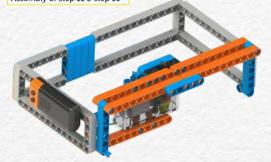


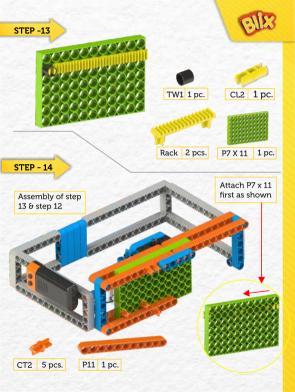














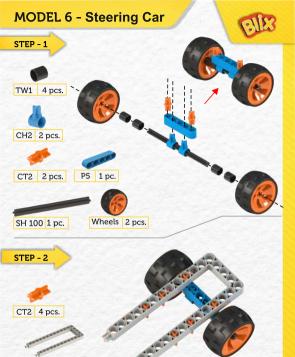






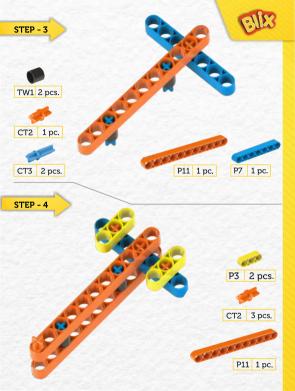






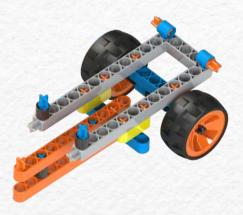
PU5 X 13

1 pc.





Assembly of step 4 & step 2





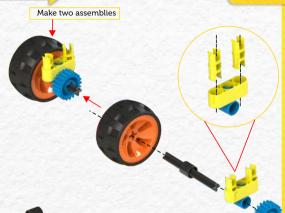


















CL2 4 pcs. P3 2 pcs.









Wheels 2 pcs. G(20) 2 pcs. SH60 2 pcs. CH2 2 pcs.

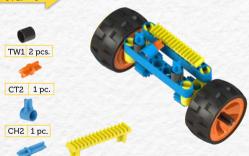




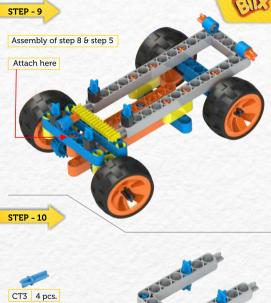


P7 2 pcs.

CT3 2 pcs.

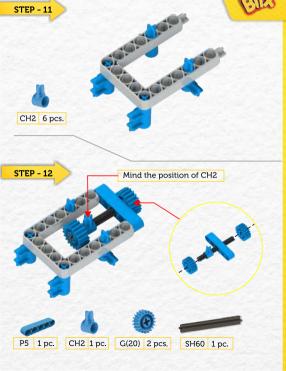


Rack 1 pc.

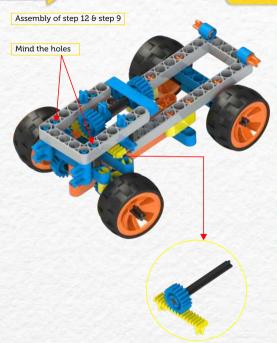










































P7 X 11 1 pc.







Remover Tool 1 pc.









