

# MECHANICS Laboratory

## LIFTING EQUIPMENT

### Models 1 to 30

- 1 - Stacking two beams
- 2 - Stacking beams with two pegs
- 3 - Joining beams
- 4 - Stacking three beams
- 5 - Stacking beams perpendicularly
- 6 - Stacking with an L-shaped beam
- 7 - Build a square with beams
- 8 - Stacking four beams
- 9 - Build a cuboid
- 10 - Build a simple bridge
- 11 - Assemble cogwheels on a rod
- 12 - Using pulleys
- 13 - Build a Class 1 lever: pincers
- 14 - Build a Class 2 lever: nutcracker
- 15 - Build a Class 2 lever: wheelbarrow
- 16 - Build a Class 3 lever: tongs
- 17 - Build the lever's fulcrum and weight
- 18 - Assemble and test a mechanically advantaged lever
- 19 - Assemble and test a mechanically neutral lever
- 20 - Assemble and test a mechanically disadvantaged lever
- 21 - Assemble a balance
- 22 - Build and test a see-saw
- 23 - Assemble the test stand for reverse rotation
- 24 - Build and test forward rotation
- 25 - Assemble and test alternating movement
- 26 - Build and observe right-angle rotation
- 27 - Assemble a vertical gearbox
- 28 - Build a horizontal to vertical gearbox
- 29 - An ancient war machine: the battering-ram
- 30 - Assemble a manual gearbox with gears



#### WARNING

In order to ensure correct function of the electric motor, a small quantity of grease is added during the manufacturing process. As grease can melt at high temperatures, it may dirty the motor. However, it can simply be wiped off with a piece of kitchen paper or a napkin. The grease used is neither toxic nor hazardous.

#### WARNING!

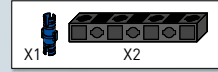
Suitable for children aged 8 years and older.

The instructions for adults are included and must be observed.

Read and keep this manual for future reference.

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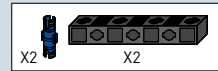
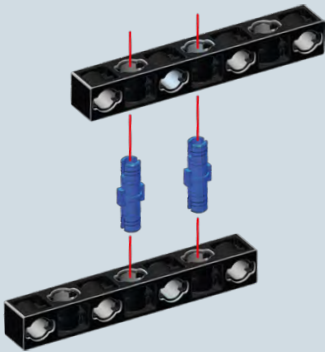
## 1 Stacking two beams



Assembled beams

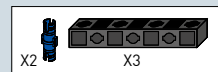
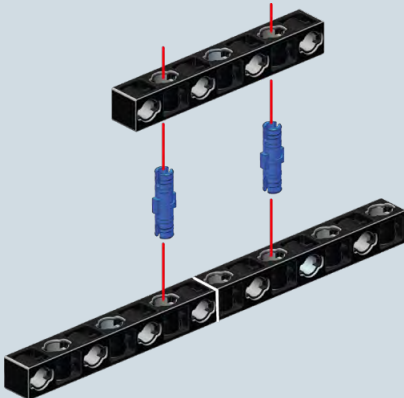
## 2 Stacking beams with two pegs

Two pegs make the construction very robust!



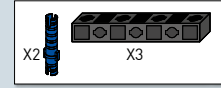
Assembled beams

## 3 Joining beams

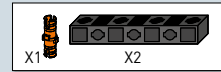
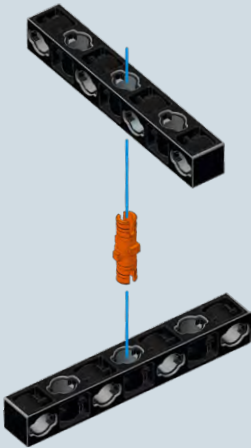


Assembled beams

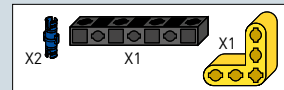
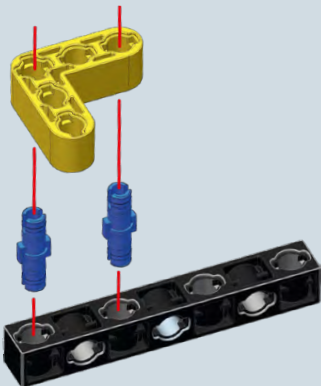
#### 4 Stacking three beams



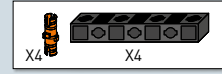
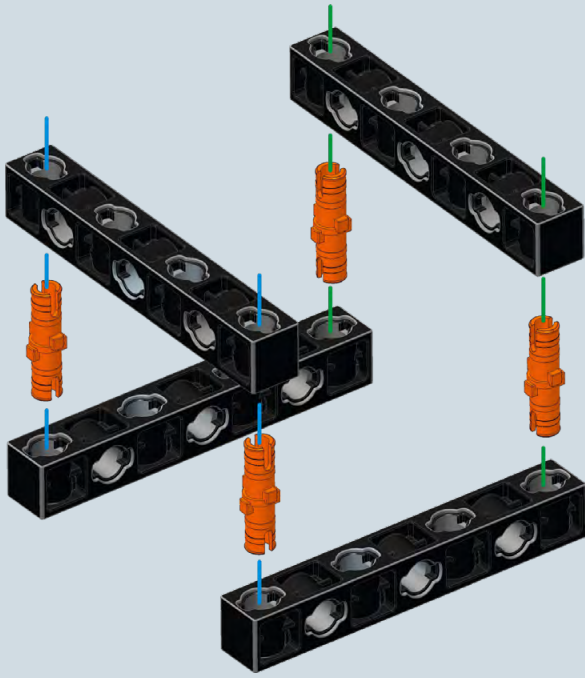
#### 5 Stacking beams perpendicularly



#### 6 Stacking with an L-shaped beam

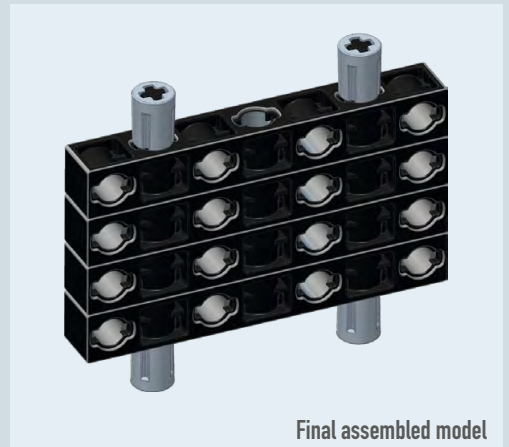
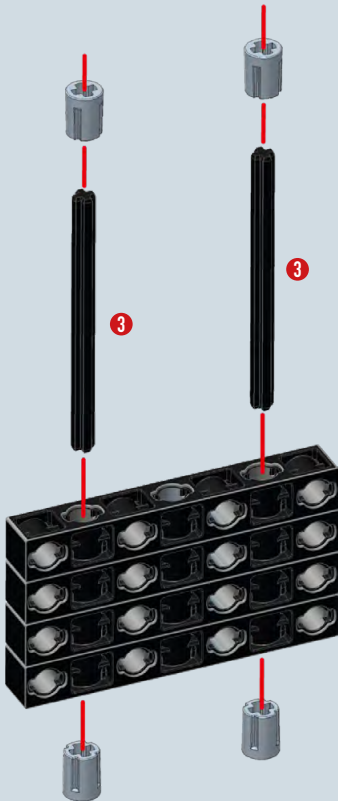


## 7 Build a square with beams



Final assembled model

## 8 Stacking four beams

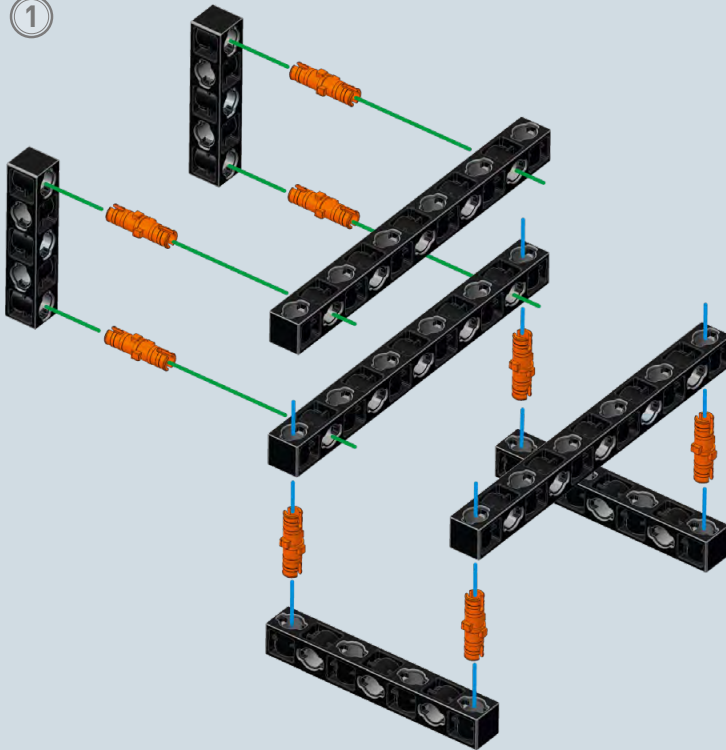


Final assembled model





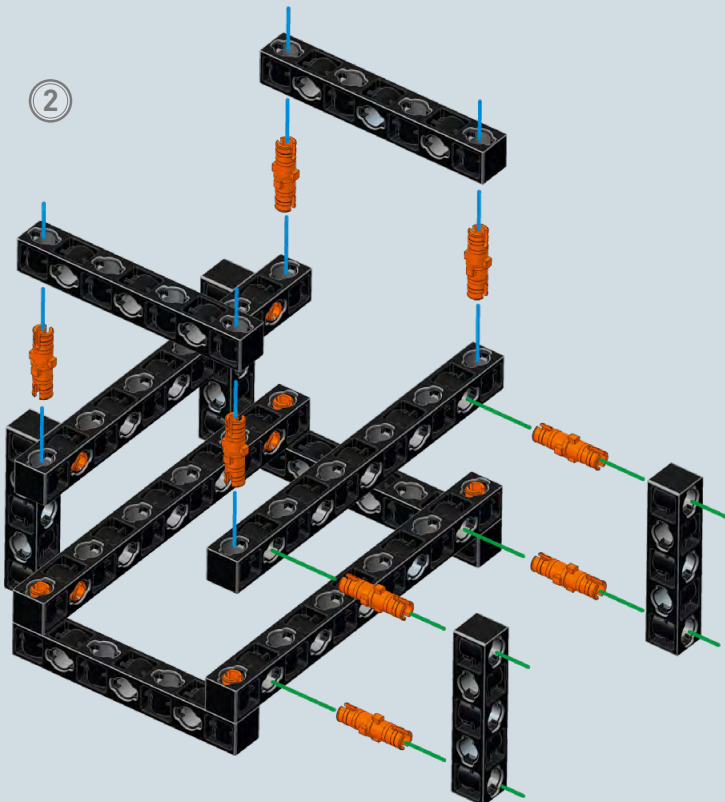
1



- X3
- X8
- X2
- X2



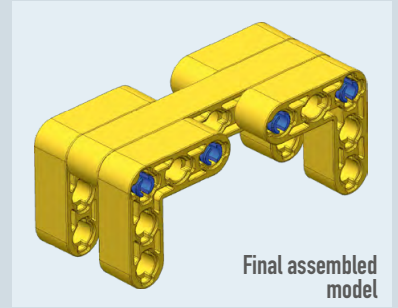
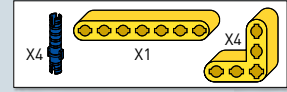
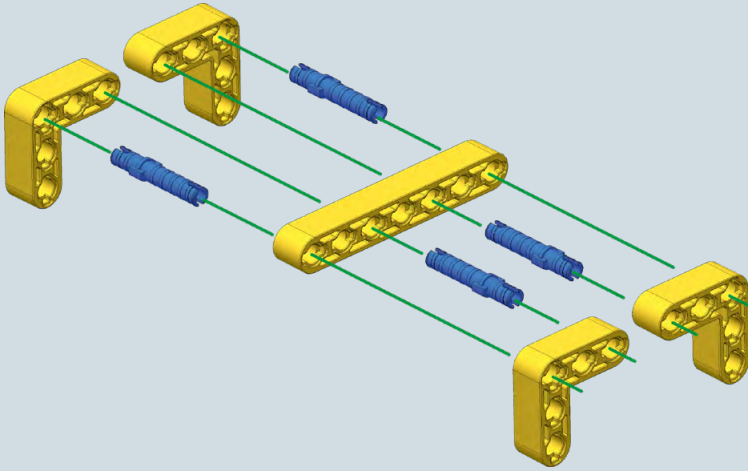
2



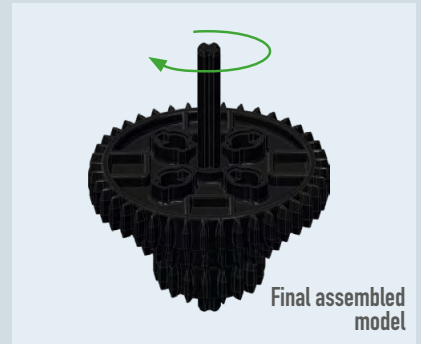
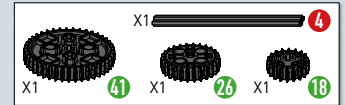
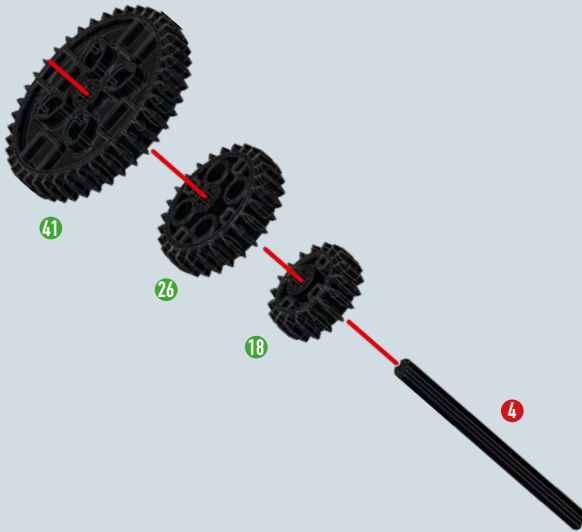
- X1
- X8
- X2
- X2



## 10 Build a simple bridge

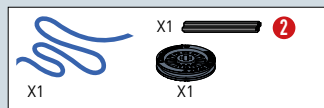


## 11 Assemble cogwheels on a rod



Try it out as a spinning top!

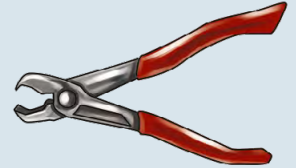
## 12 Using pulleys



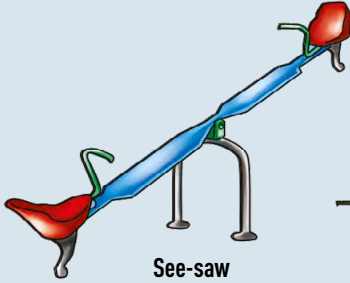
Since ancient times humans have made use of many of these mechanisms to increase their strength and enable them to accomplish great feats which can still be admired today.



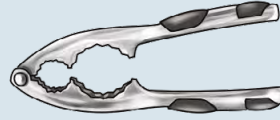
Wheelbarrow



Pincers



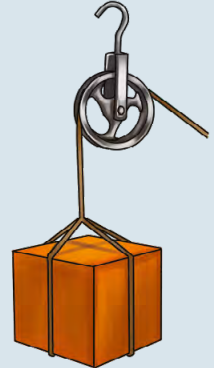
See-saw



Nutcracker



Balance

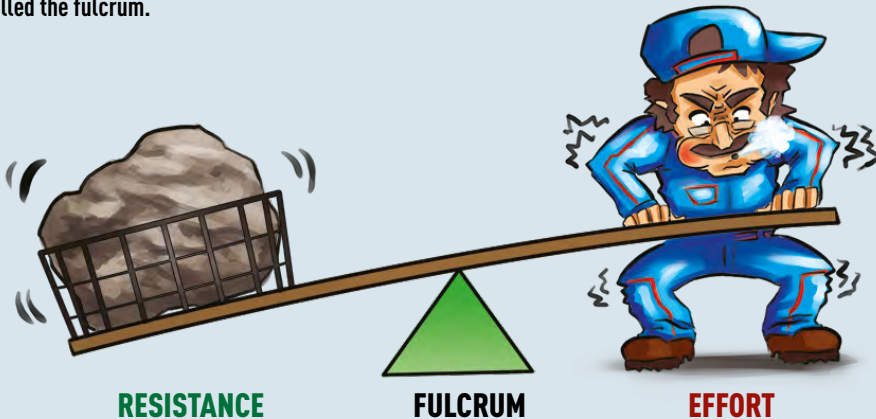


Pulley

A simple machine is an instrument that allows for balancing and overcoming **RESISTANCE** (weight, resistance force = **R**) with **EFFORT** (manpower = **E**).

## LEVERS

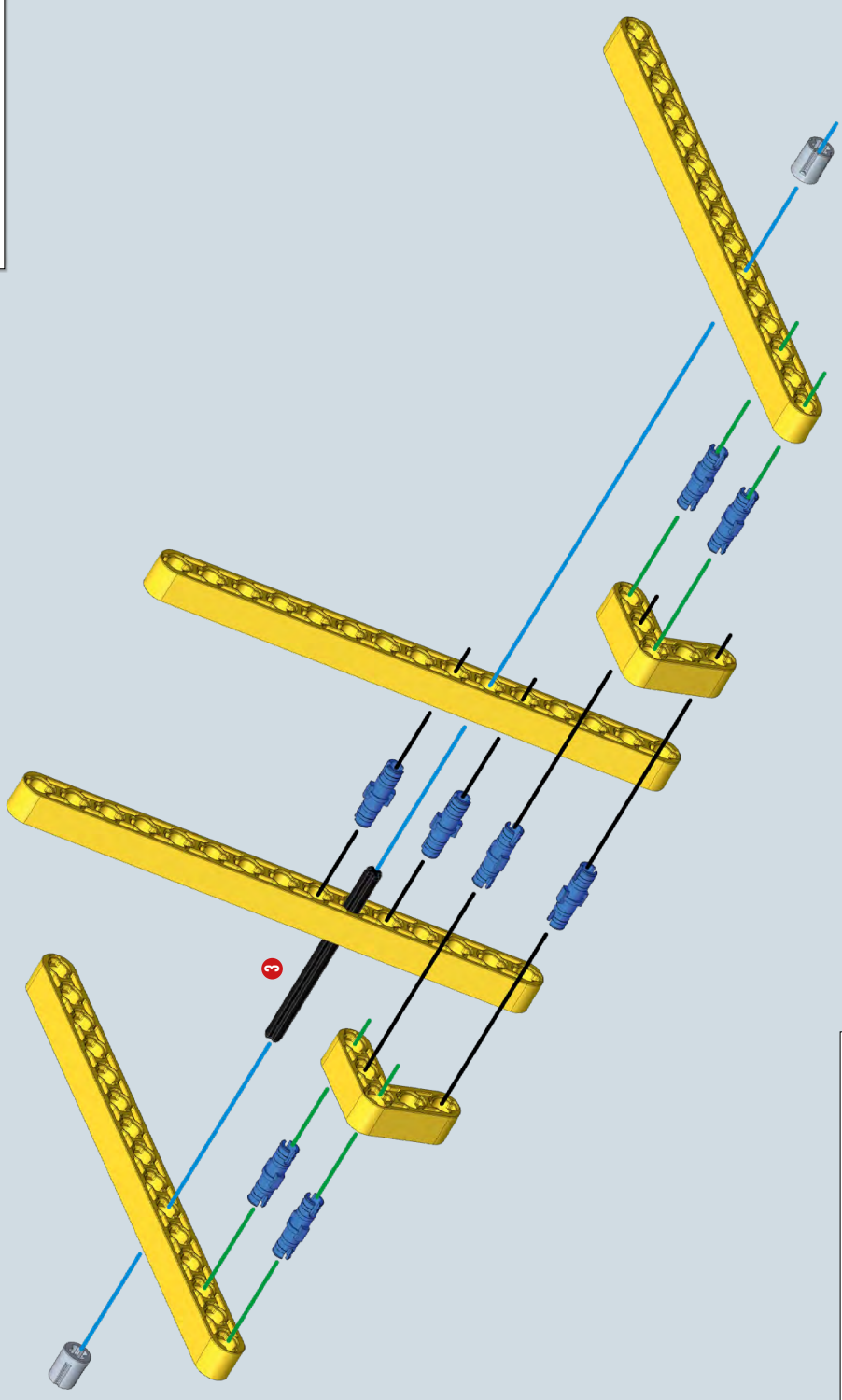
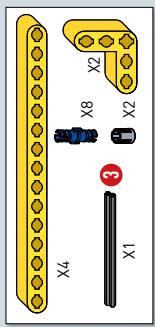
A lever is a simple machine that is made up of a rigid bar which can rotate around a fixed point called the fulcrum.



- Pairs of levers also obey this principle.
- Levers are classified on the basis of the relative position of the **EFFORT**, **RESISTANCE** and **FULCRUM**.

13 Build a Class 1 lever: pincers

1



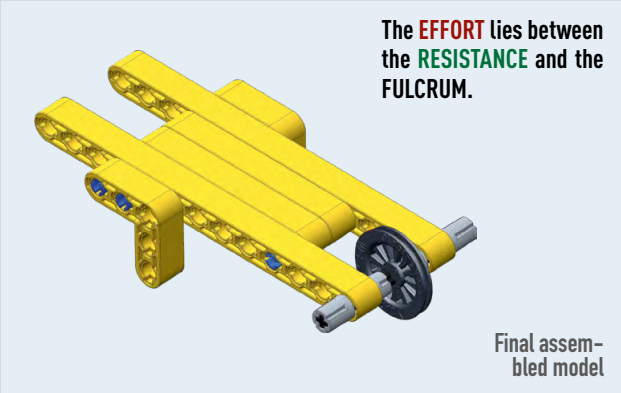
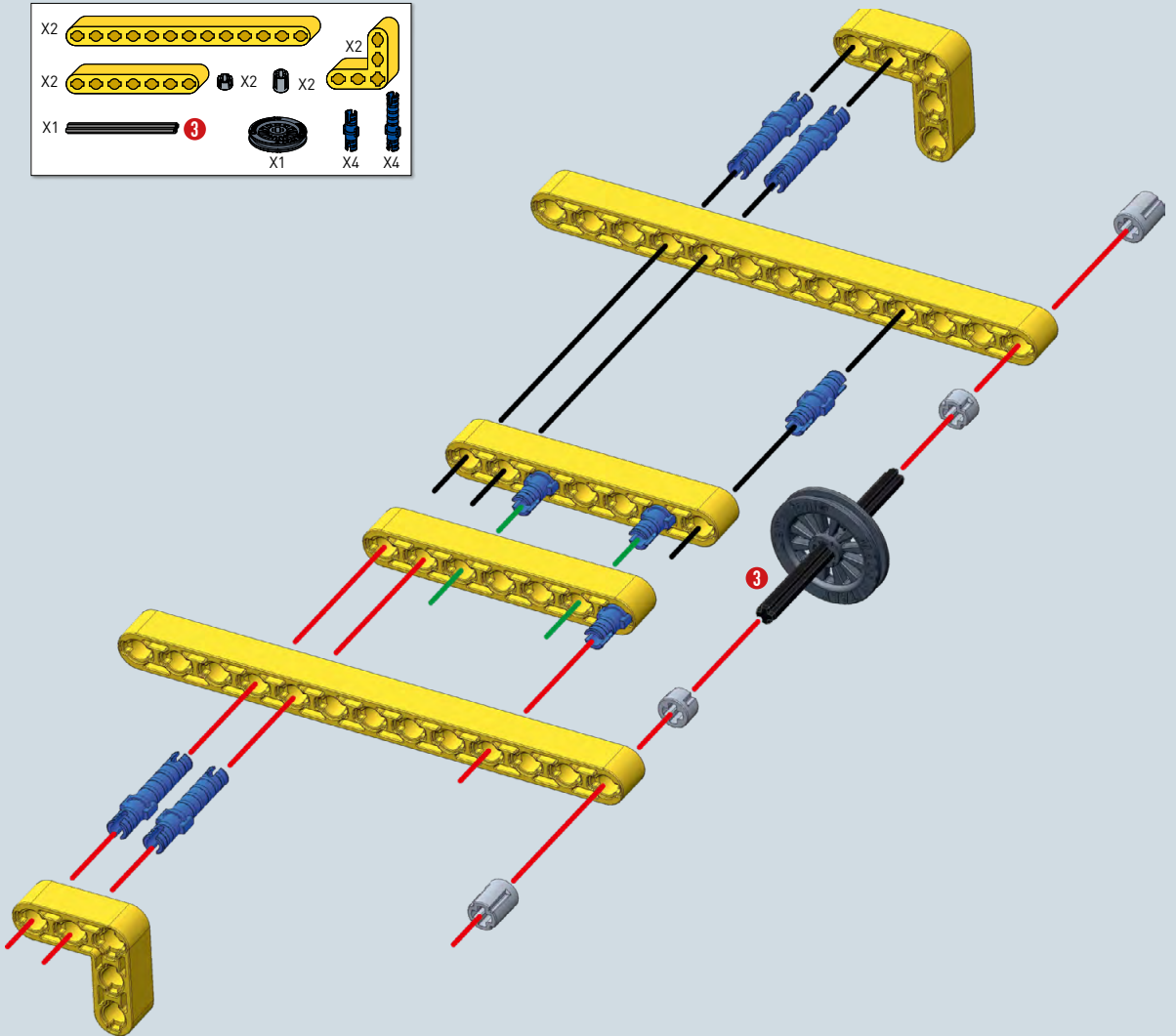
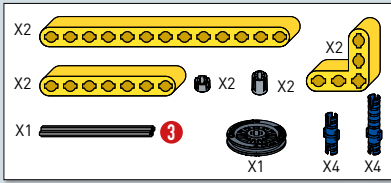
1:1



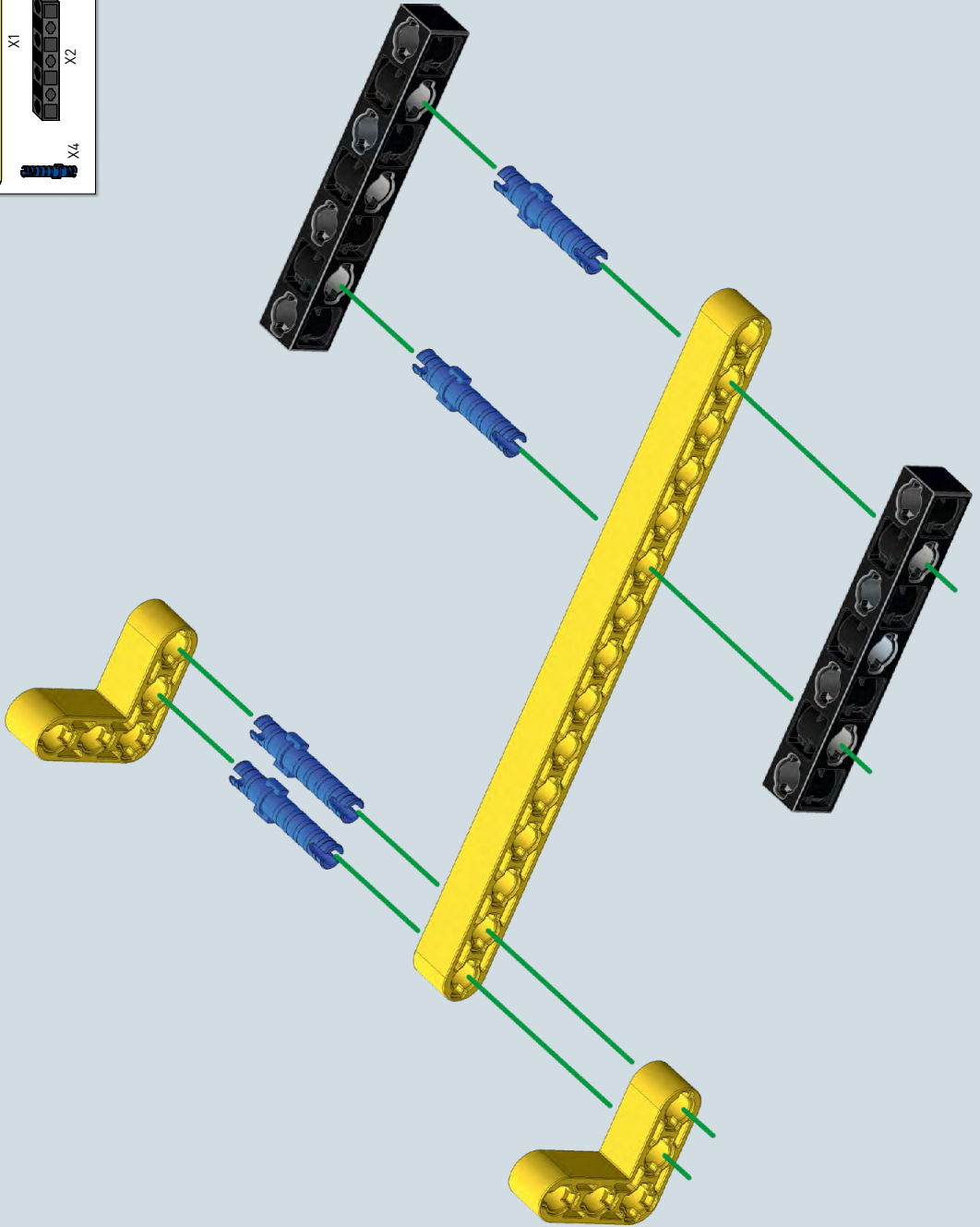
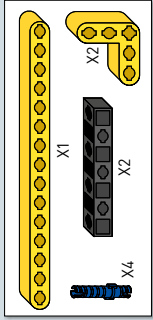


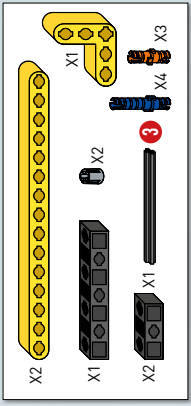


# 15 Build a Class 2 lever: wheelbarrow

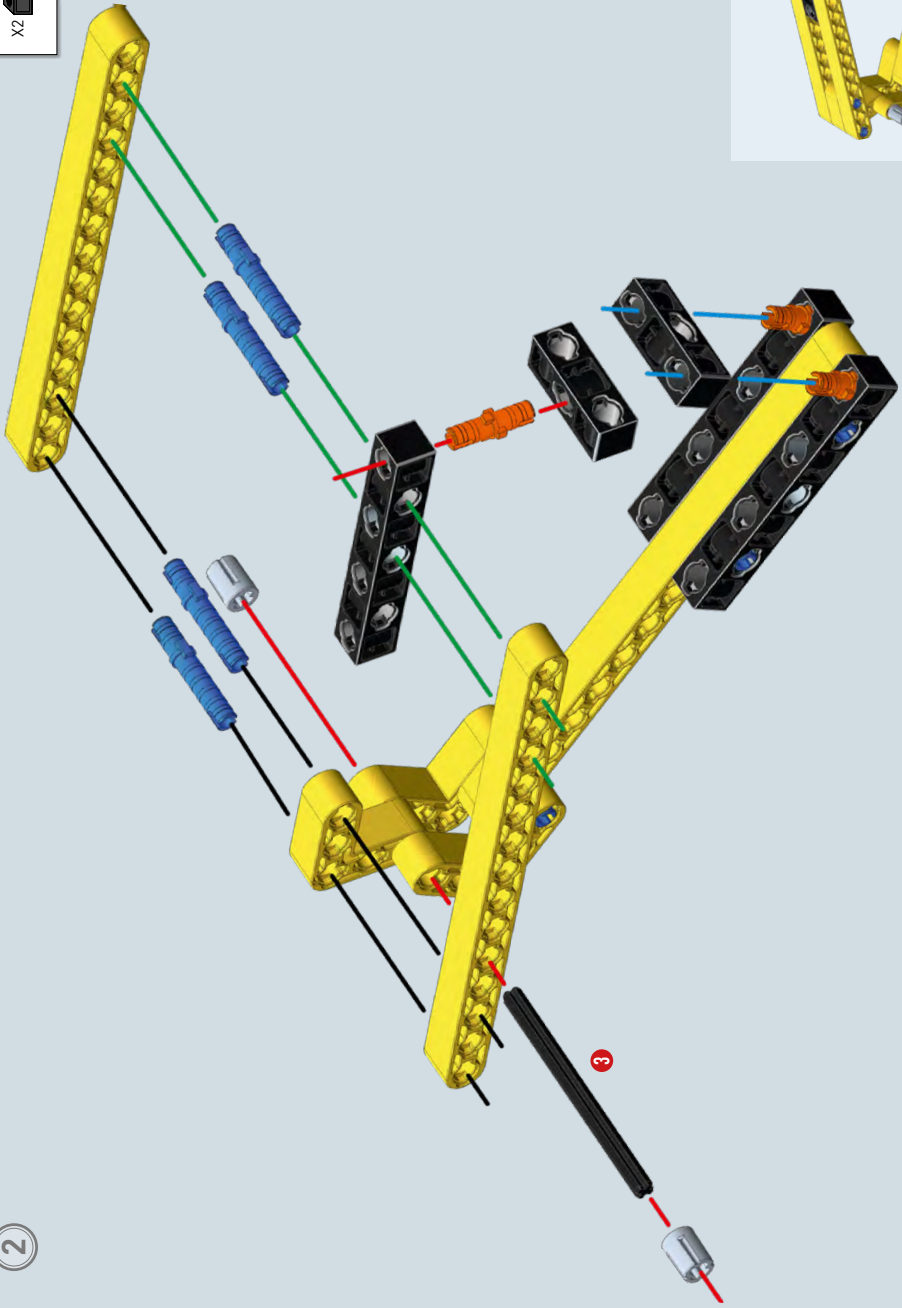


1





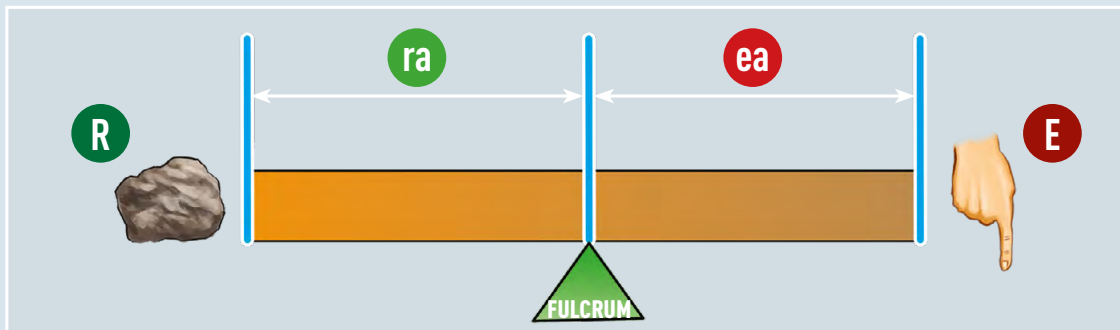
2



Final assembled model



The lever is a simple machine built by man to perform work by reducing the force required. Two forces are applied to the rod: the **EFFORT** and the **RESISTANCE**. Using a lever, therefore, we have a **MECHANICAL ADVANTAGE** that can be calculated by considering also the length of the **EFFORT** and of the **RESISTANCE**. In the lever, the lengths of the arms correspond to the distances from the fulcrum.



- Key:
- ea = EFFORT arm
  - ra = RESISTANCE arm
  - E = EFFORT force
  - R = RESISTANCE force

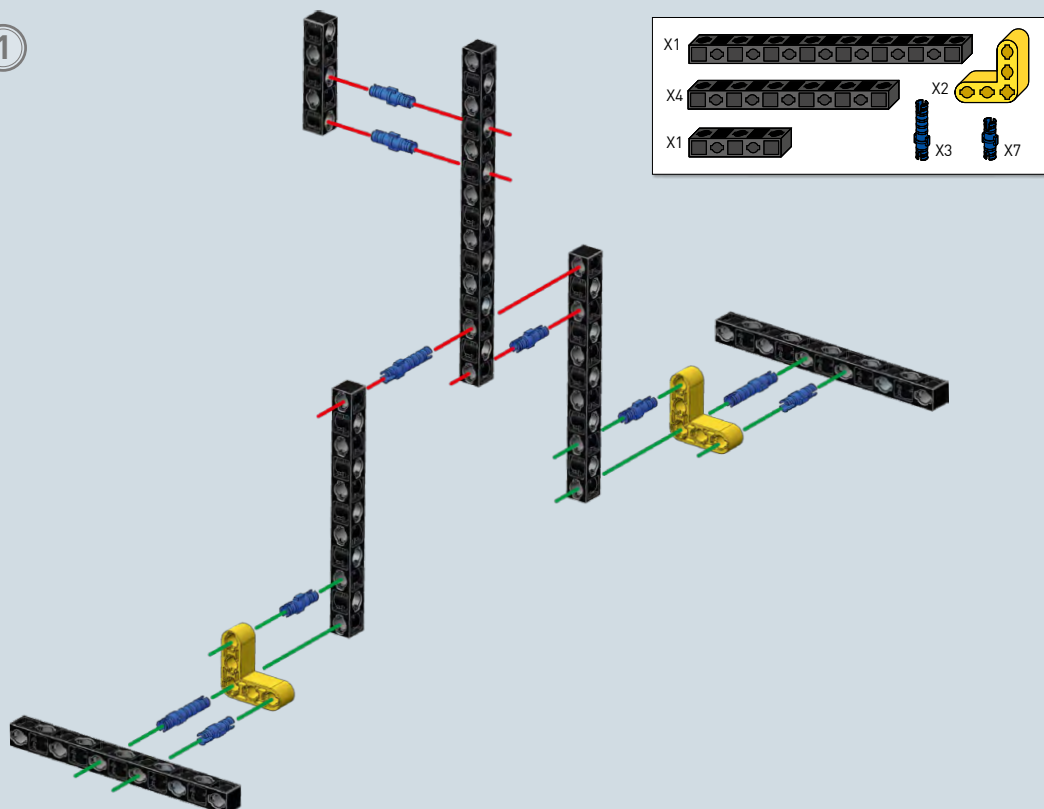
EQUILIBRIUM CONDITIONS  $ra \times R = ea \times E$

MECHANICAL ADVANTAGE  $A = R / E$

## ASSEMBLE AND TEST THE LEVERS

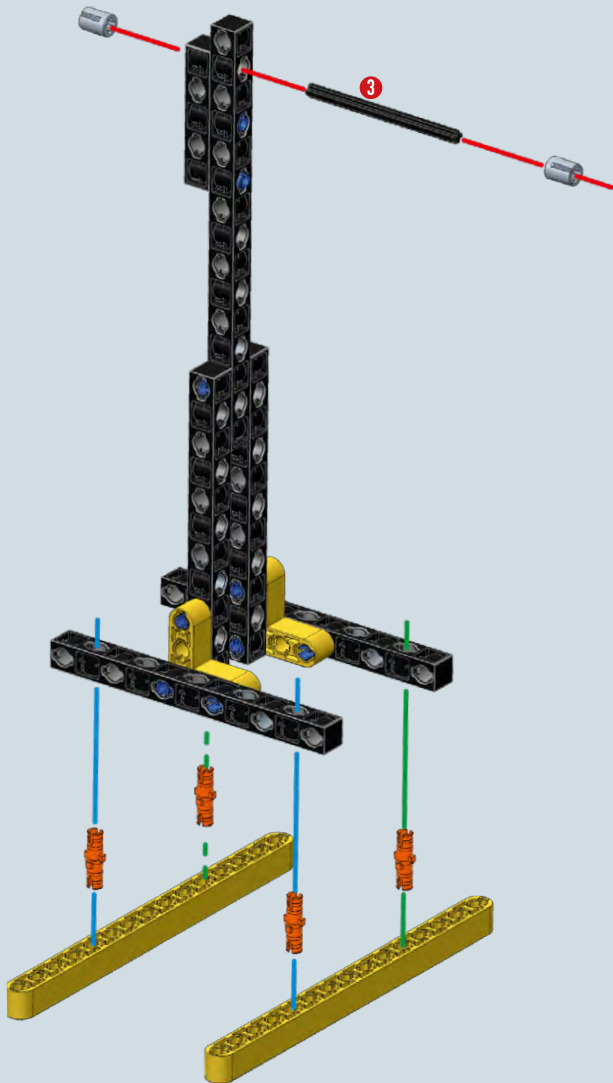
### 17 Build the lever's fulcrum and weight

1





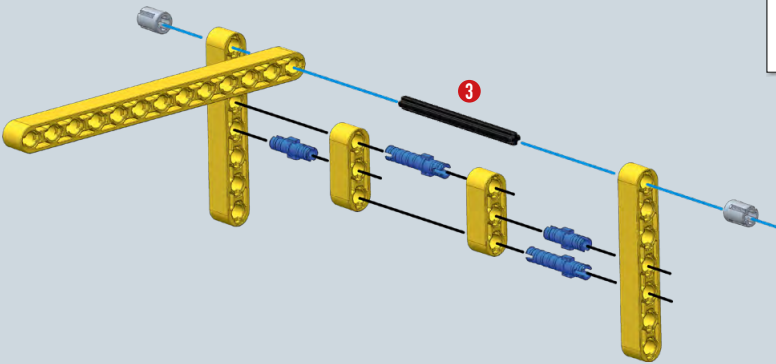
2



X2

X1 3 X2

### ASSEMBLING THE WEIGHT

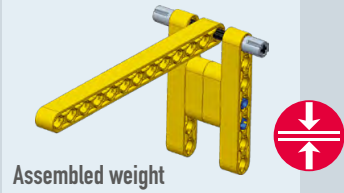


X1

X2

X1 3 X2

X2



Assembled weight

In Activities 16-17-18 try moving the fulcrum and then applying downward pressure to the EFFORT arm with your hand to see the differences between the levers.

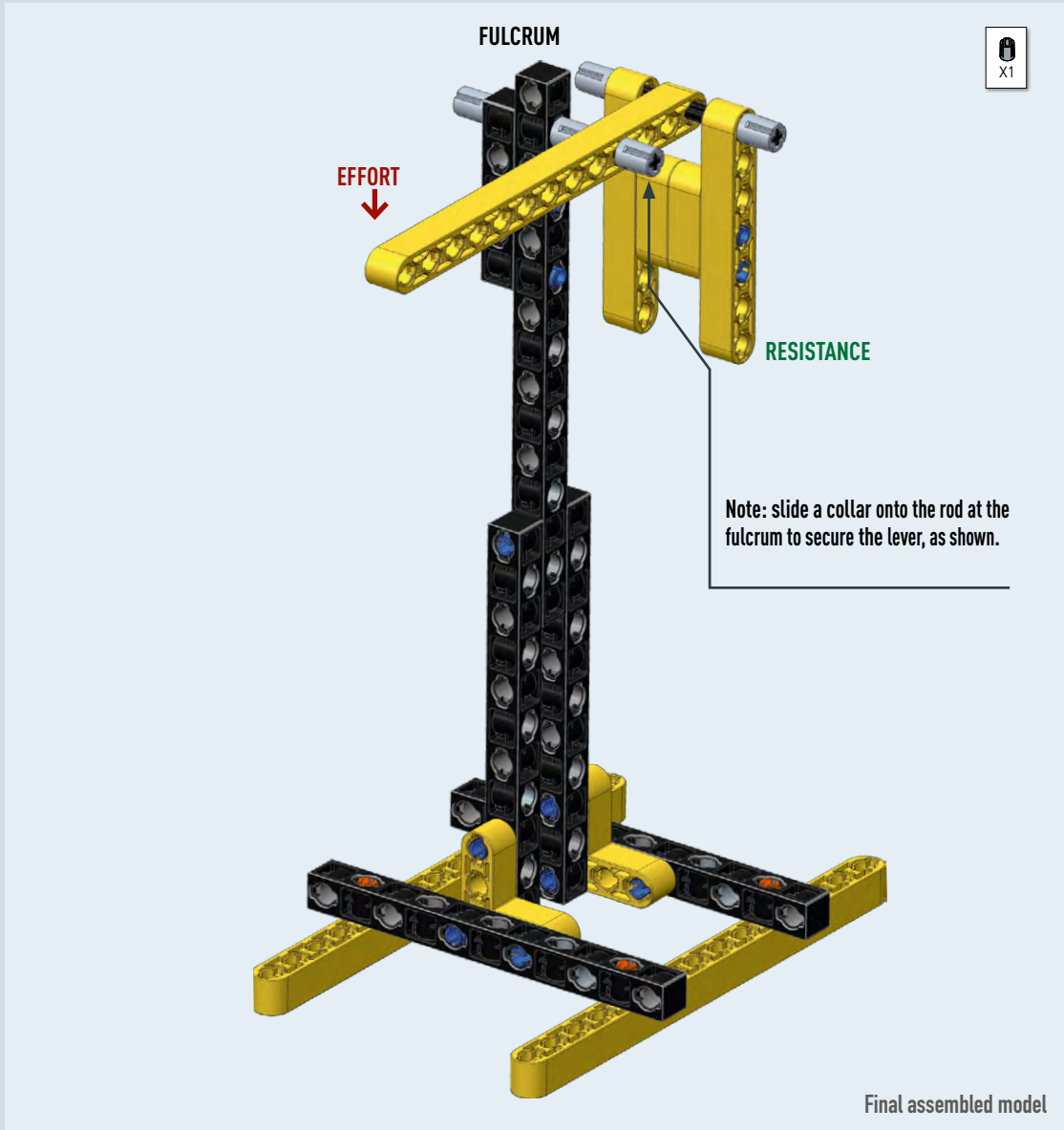
## 18 Assemble and test a mechanically advantaged lever

Find the equilibrium of this type of mechanical device: position the weight (RESISTANCE) on one side of the lever and gently press down with your hand (EFFORT) on the other side.

Note the position of the fulcrum!

- The **EFFORT** arm is longer.
- The **EFFORT** is less than the **RESISTANCE**.

**TRY IT OUT!**



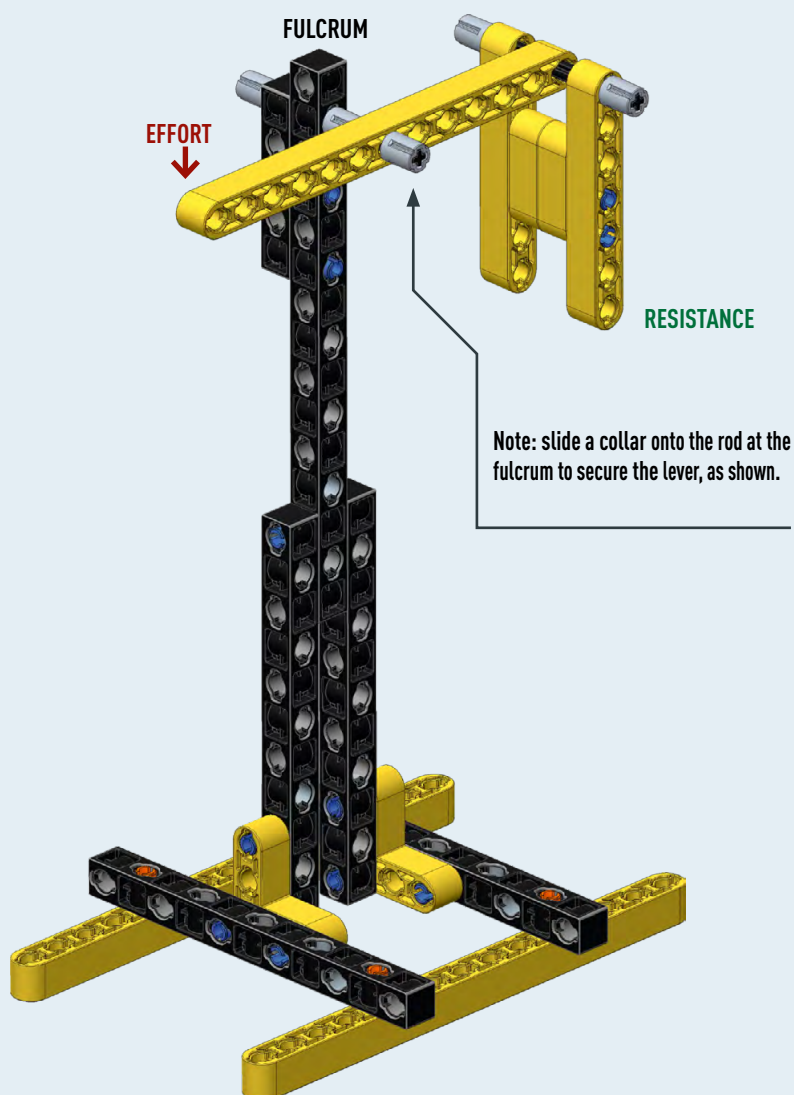
## 19 Assemble and test a mechanically neutral lever

Find the equilibrium of this type of mechanical device: position the weight (RESISTANCE) on one side of the lever and gently press down with your hand (EFFORT) on the other side.

**Note the position of the fulcrum!**

- The arms are the same.
- The **EFFORT** is equal to the **RESISTANCE**.

**TRY IT OUT!**



Final assembled model

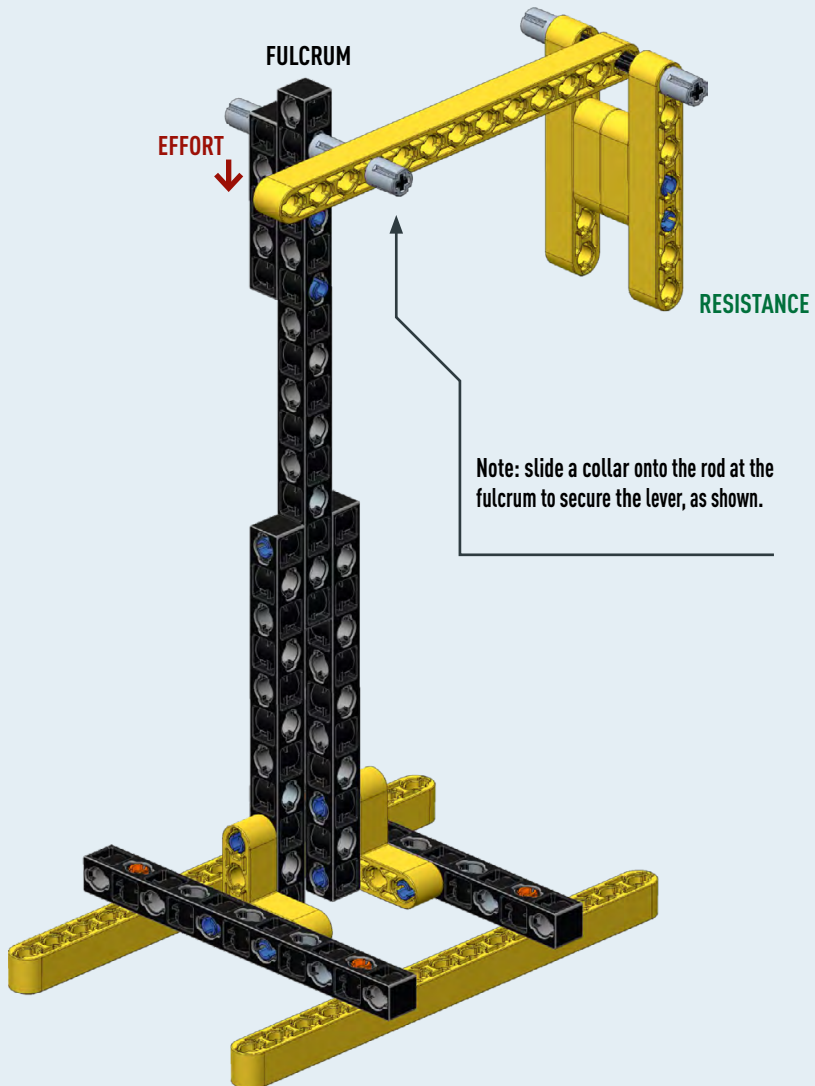
## 20 Assemble and test a mechanically disadvantaged lever

Find the equilibrium of this type of mechanical device: position the weight (RESISTANCE) on one side of the lever and gently press down with your hand (EFFORT) on the other side.

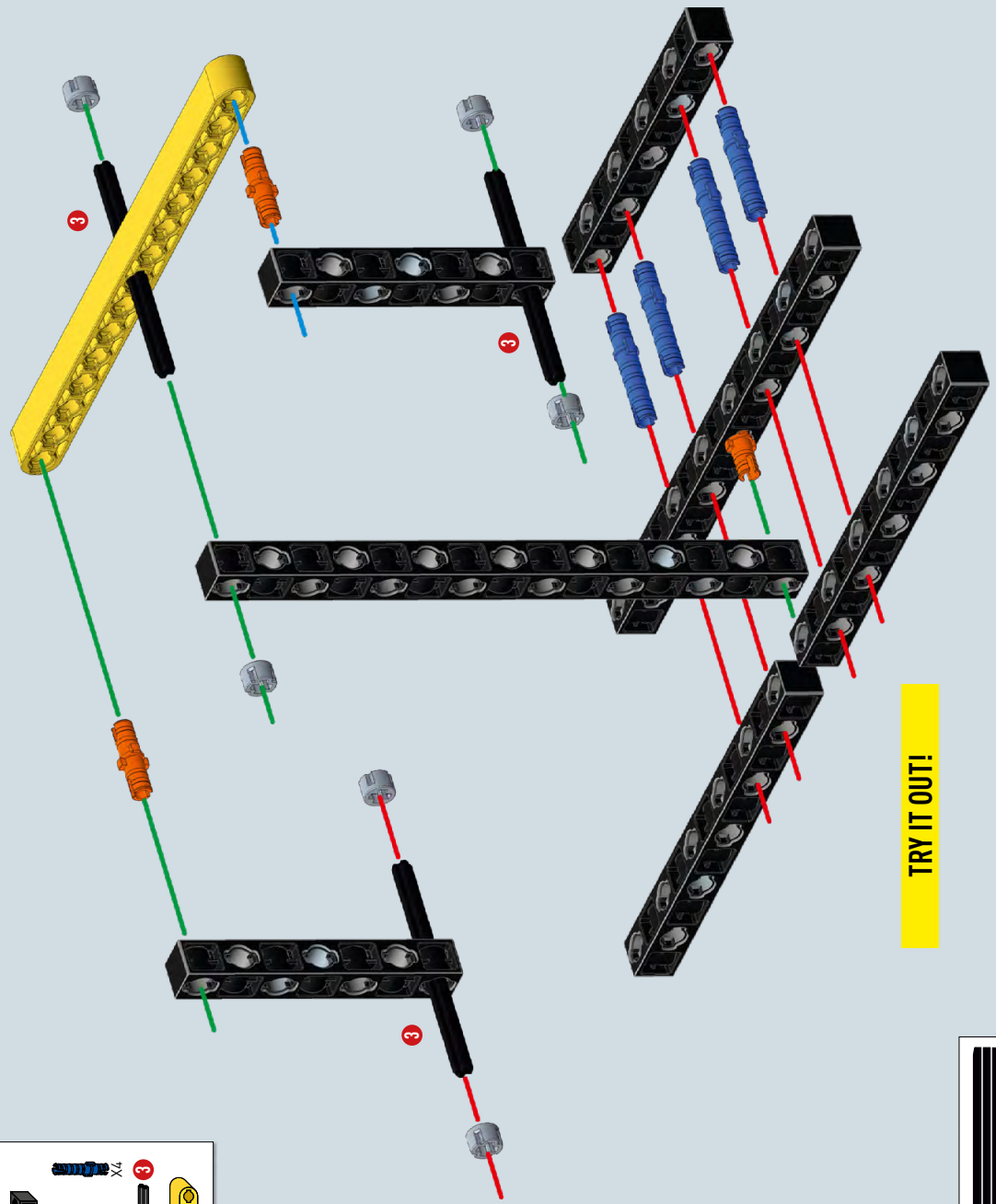
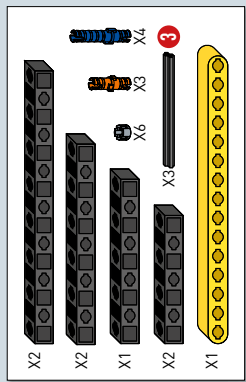
**Note the position of the fulcrum!**

- The arms are the same.
- The **EFFORT** is equal to the **RESISTANCE**.

**TRY IT OUT!**



Final assembled model



The balance is a class 1 lever










Final assembled model

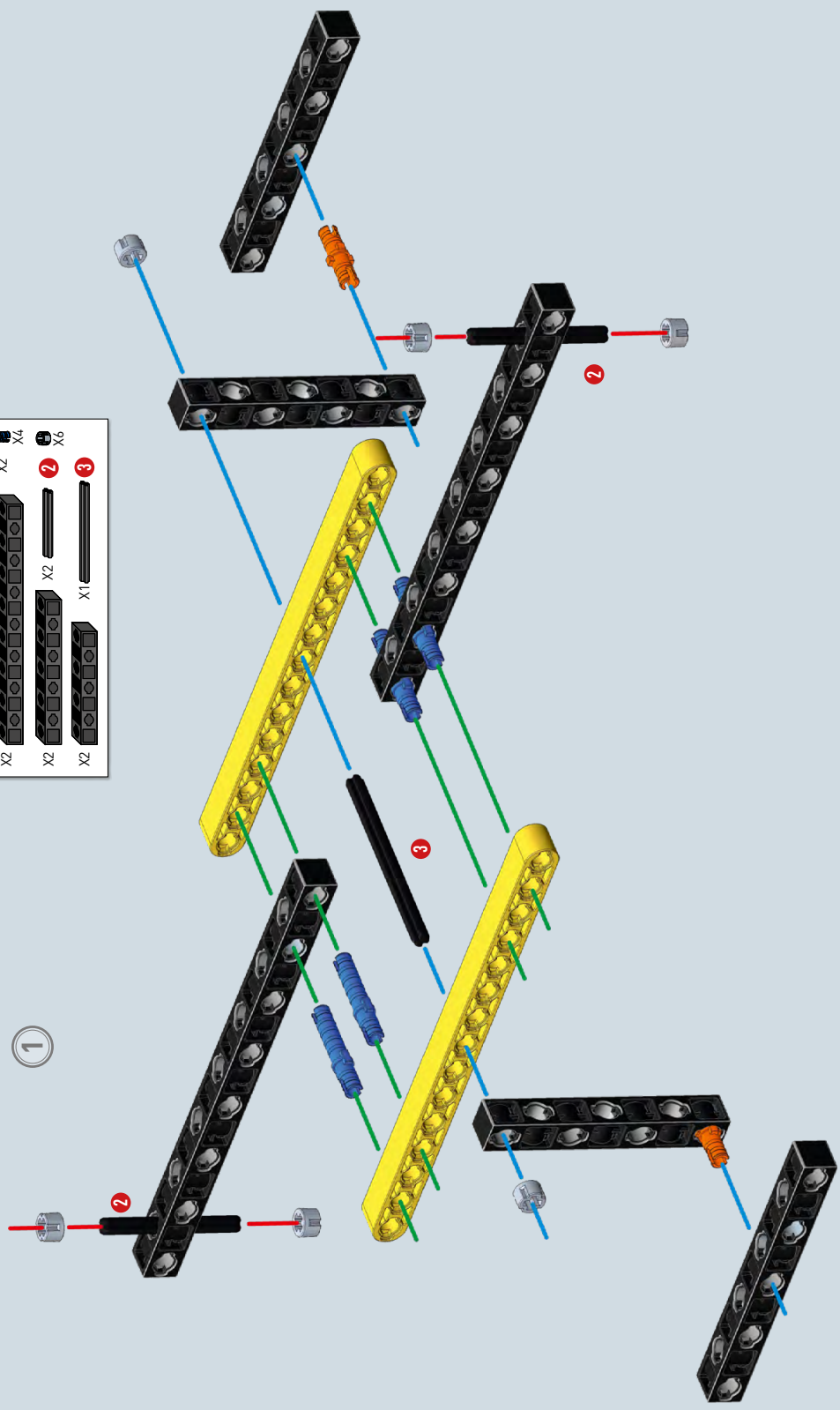
TRY IT OUT!

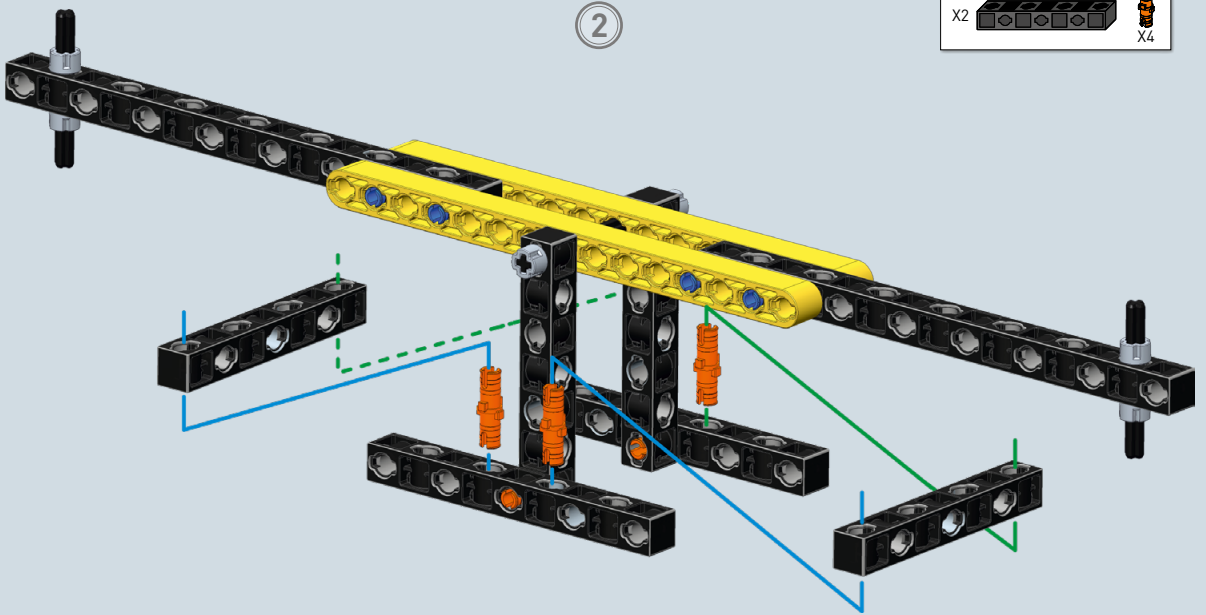


1:1



-  X2
-  X2
-  X2
-  X2
-  X4
-  X2
-  X6
-  2
-  3





In the third century BC, Archimedes was a great scientist and experimenter with levers.

**Note:** the lever of the see-saw must rotate freely around the fulcrum.

Try it yourself: find the equilibrium of the see-saw by varying the weight and distances from the fulcrum of the Resistance and Effort forces.

### TRY IT OUT!

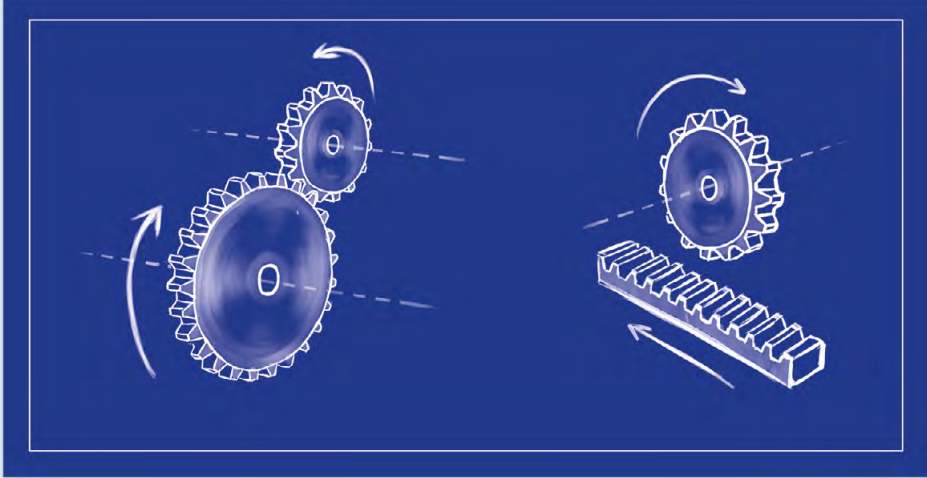


The see-saw is a class 1 lever

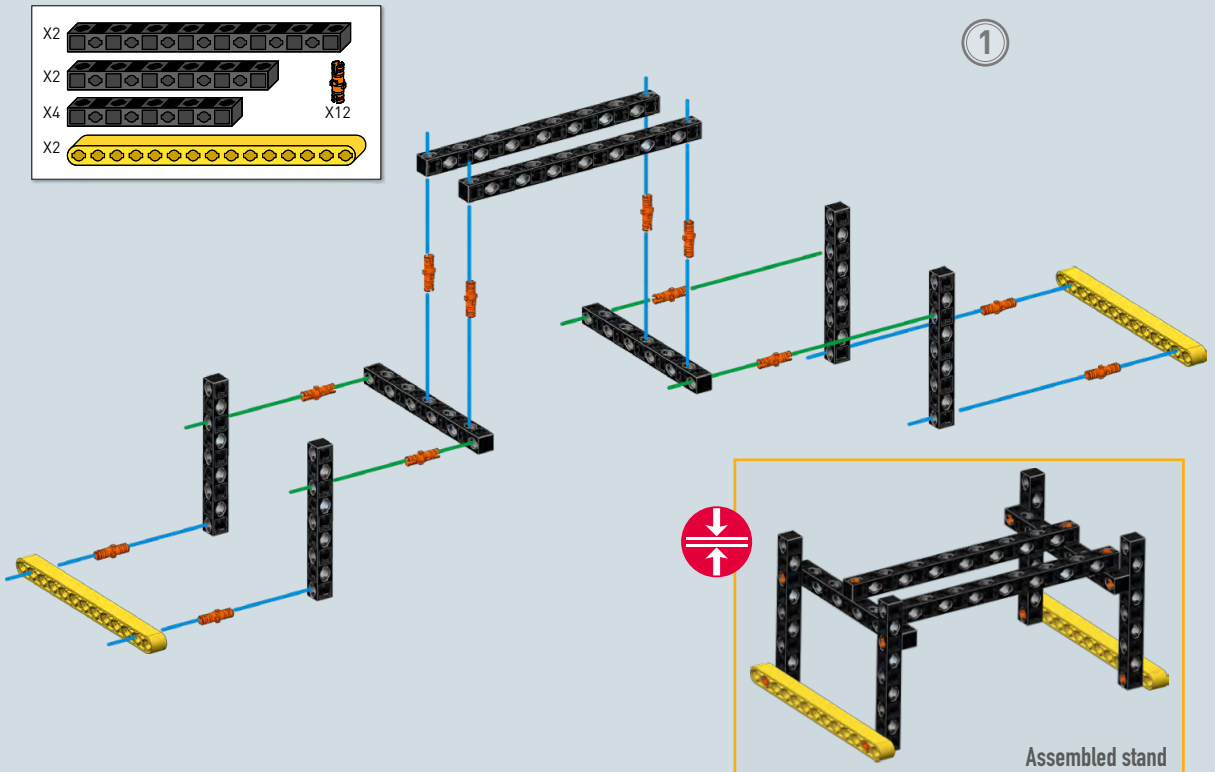
Final assembled model

Cogwheels transmit motion between suitably positioned axles (rods) via teeth.

- In a pair of cogwheels, if one cogwheel turns in one direction the other turns in the opposite direction. One of the two wheels transmits motion (drive wheel) while the other receives it (driven wheel).
- To maintain the same direction of rotation a third cogwheel *must be inserted between the two*.
- With two different cogwheels, the smaller one – having only a few teeth – is called the **pinion**, while the one with many teeth is called the **crown wheel**. Multiple cogwheels make up a gear train.

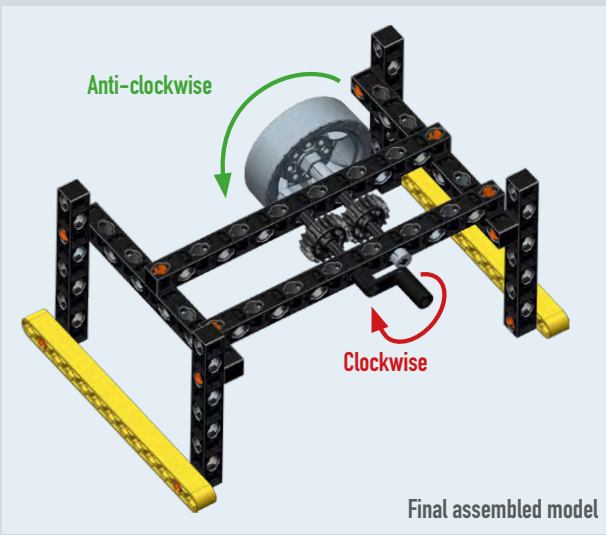
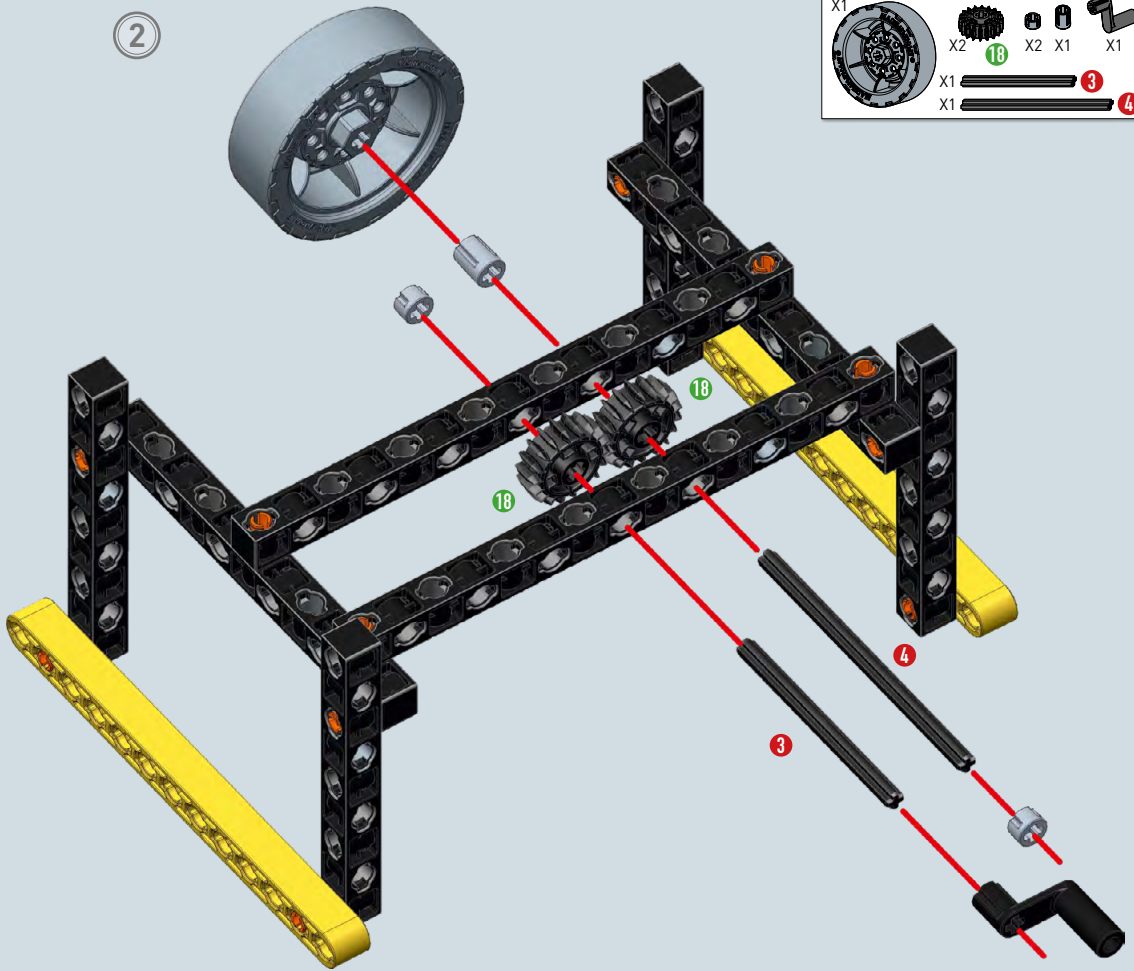


## 23 Assemble the test stand for reverse rotation



2

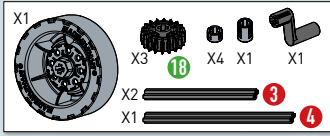
X1		X2		X2		X1		X1	
X1		X1		X1		X1		X1	



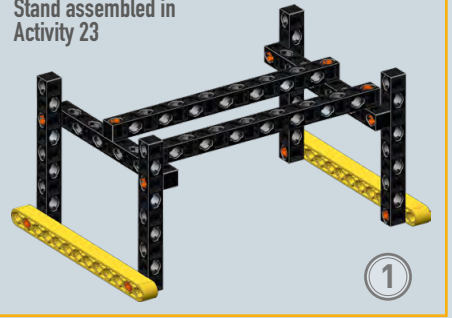
Final assembled model



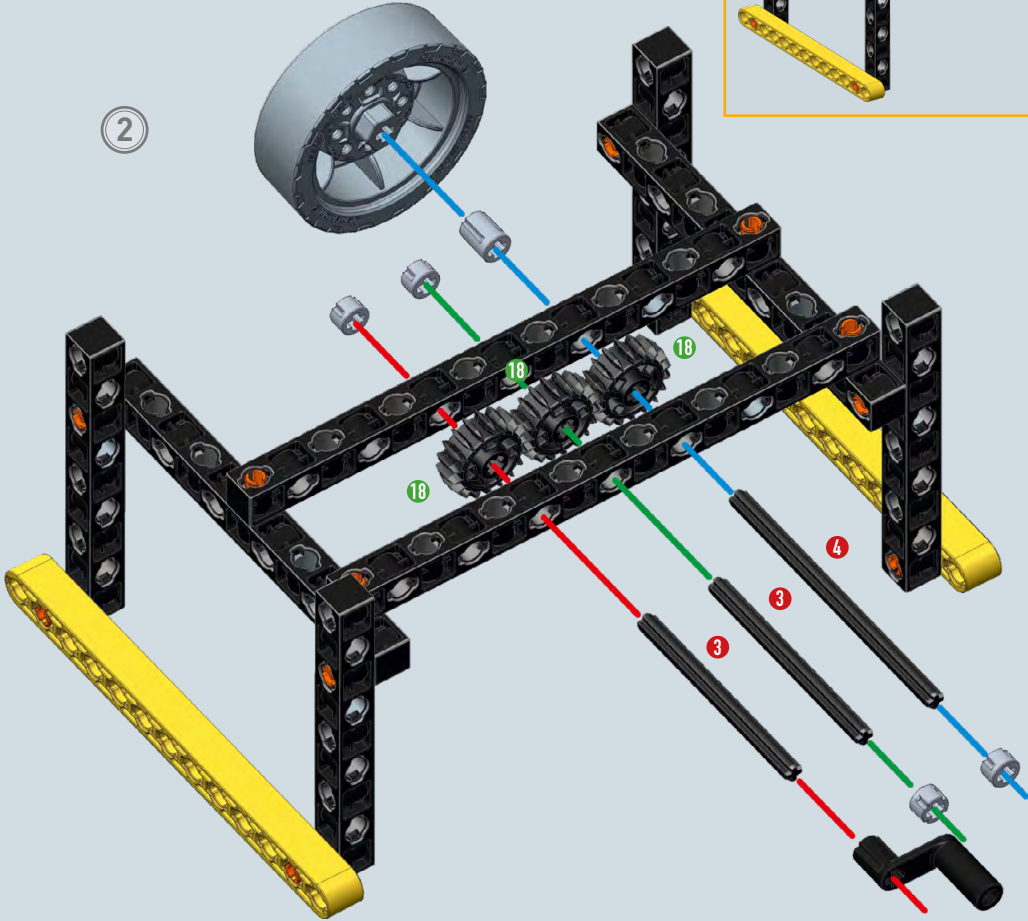
# 24 Build and test forward rotation



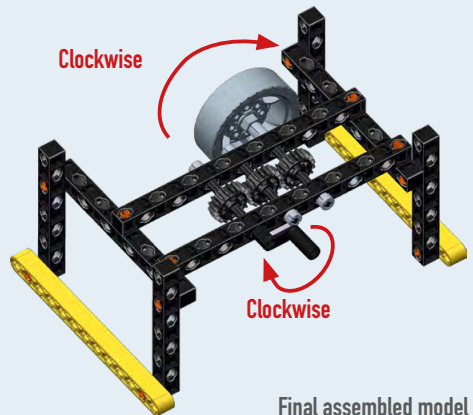
Stand assembled in Activity 23



2



Clockwise



Clockwise

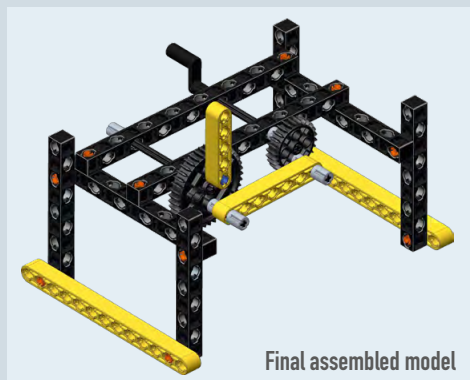
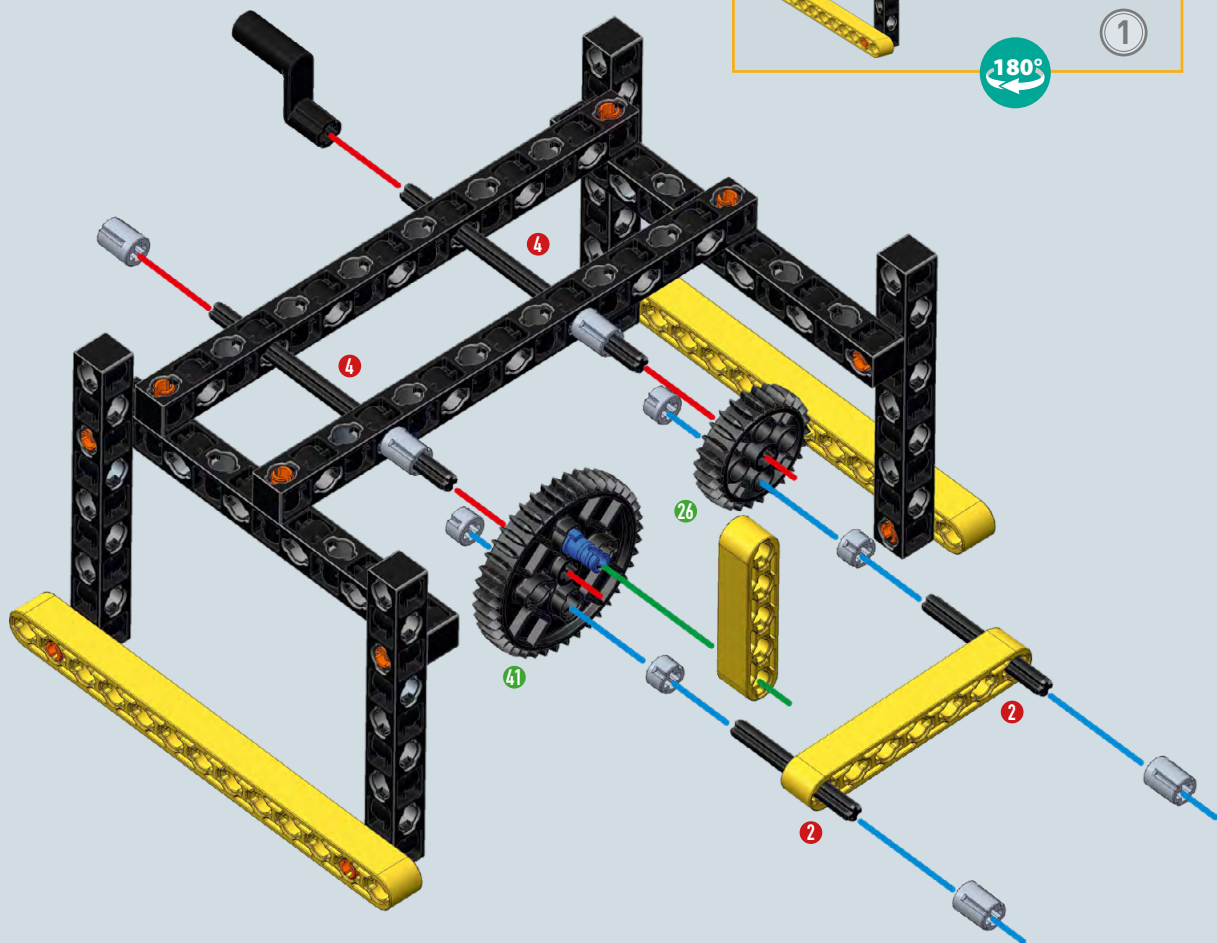
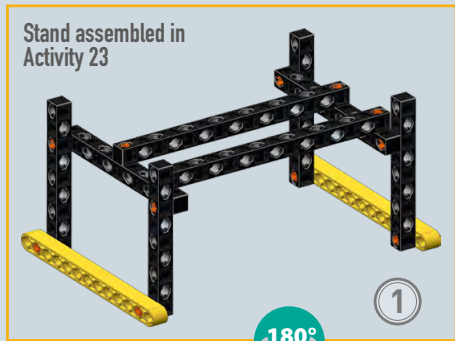
Final assembled model



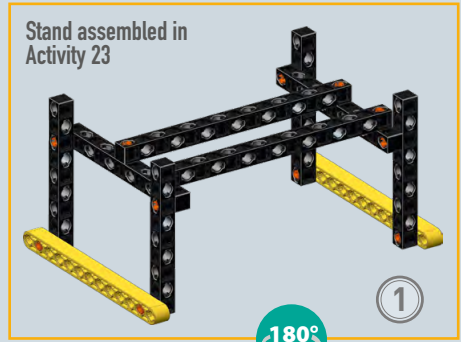
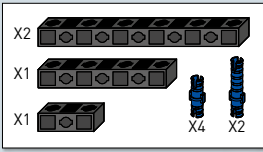


# 25 Assemble and test alternating movement

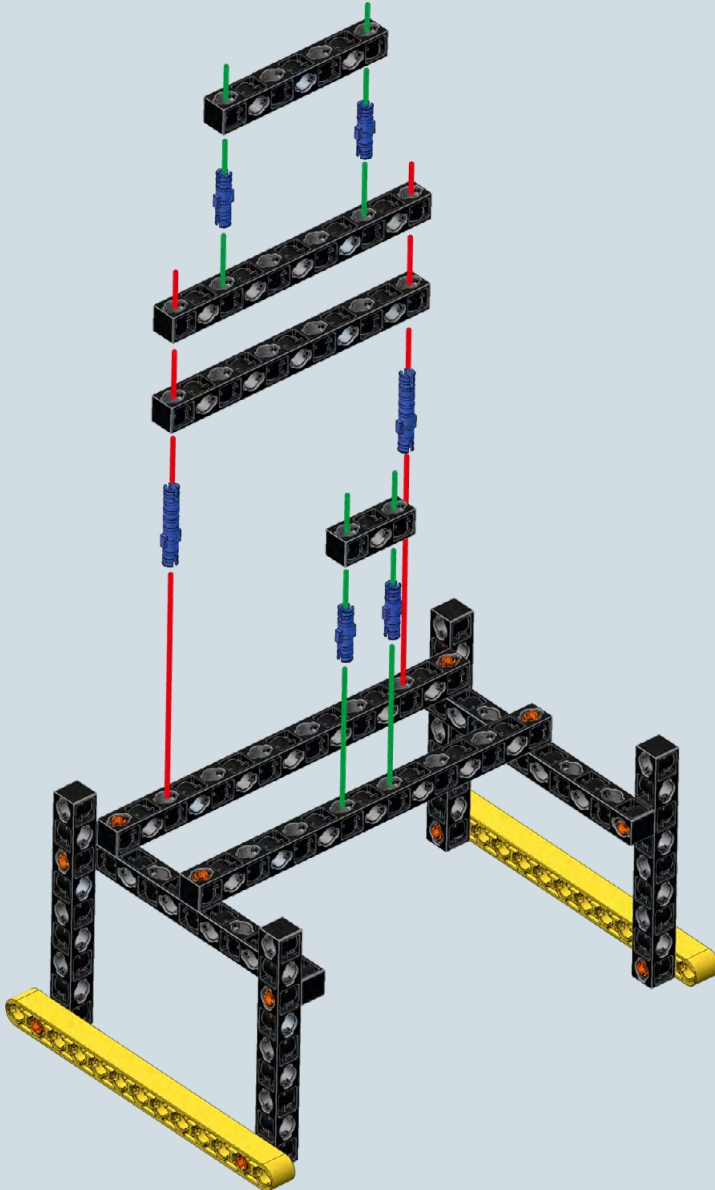
X1		X1		X1		X4	X5	X1
X2			X1					
X2			X1					



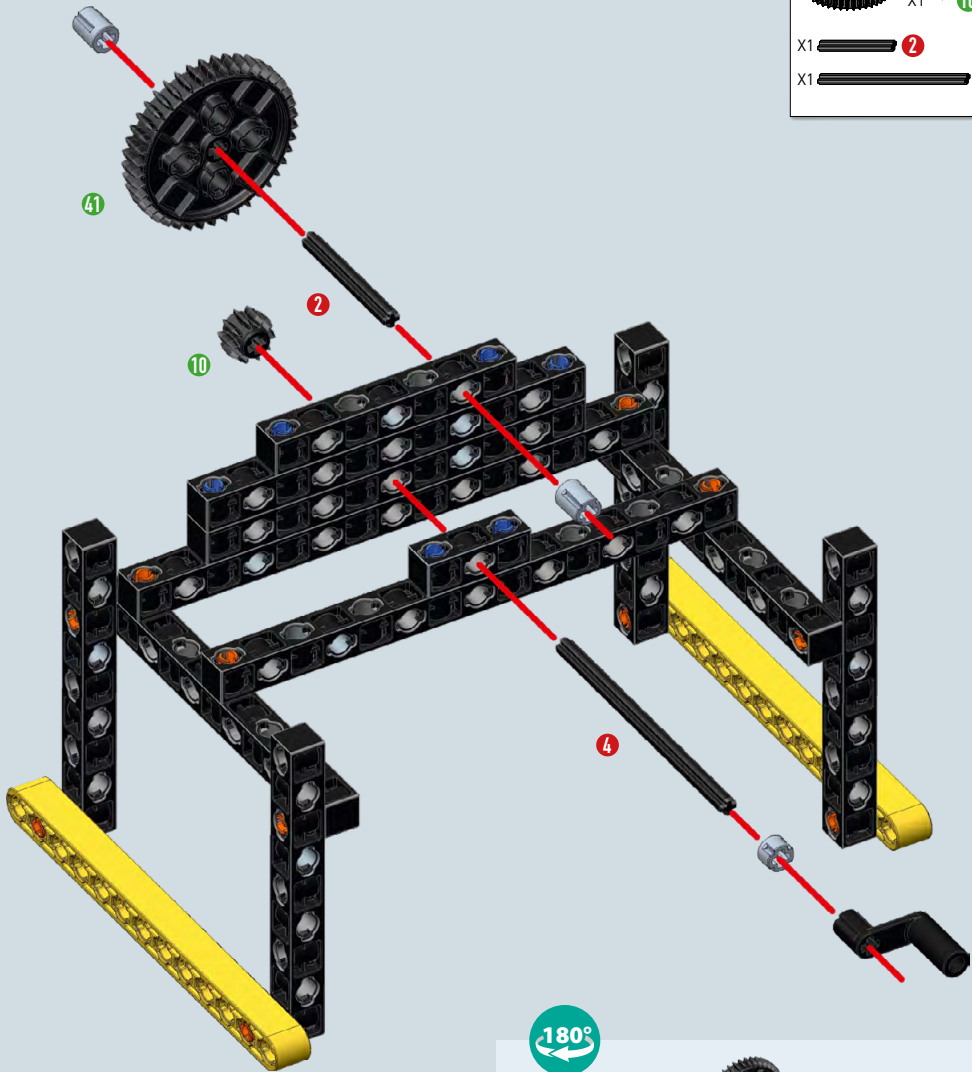




2

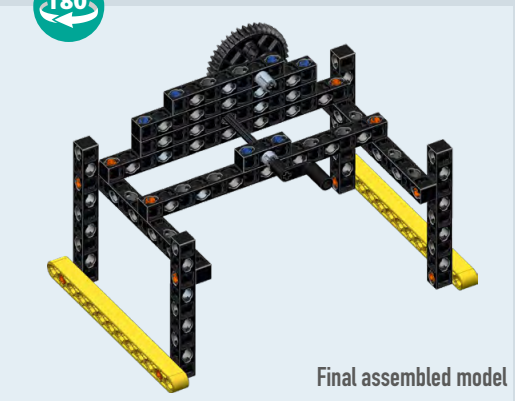


3



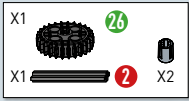
X1		X1			X1	
X1		X1		X1		X1
X1		X2				

180°

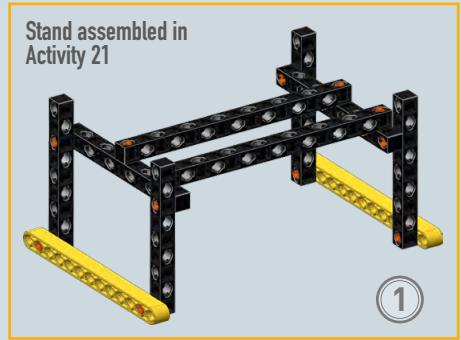
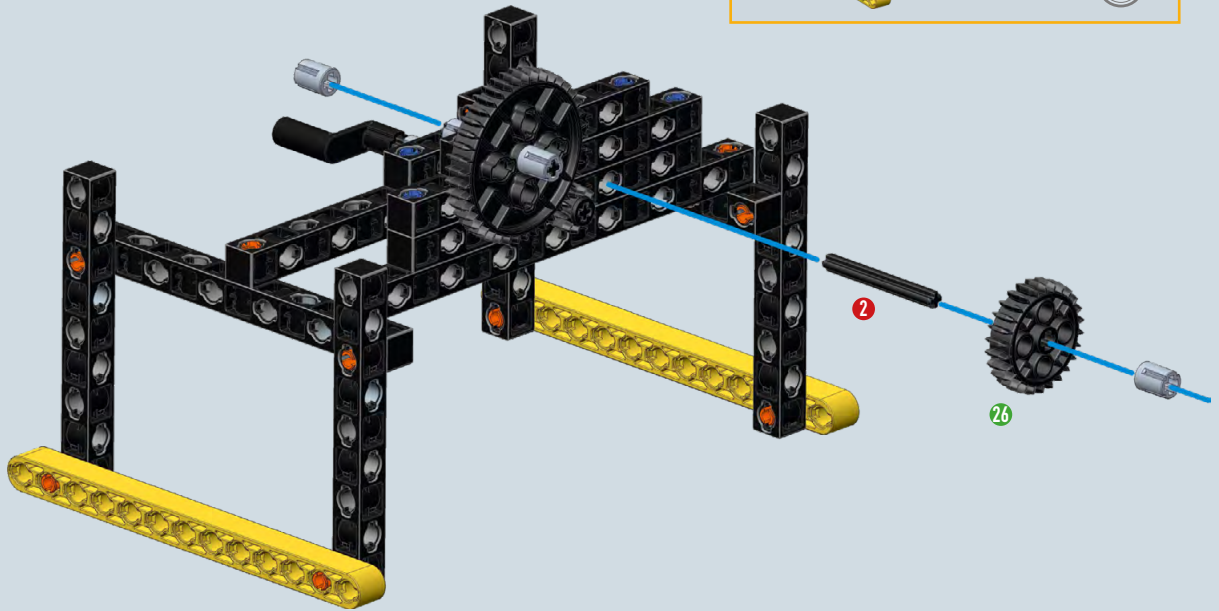


Final assembled model





2

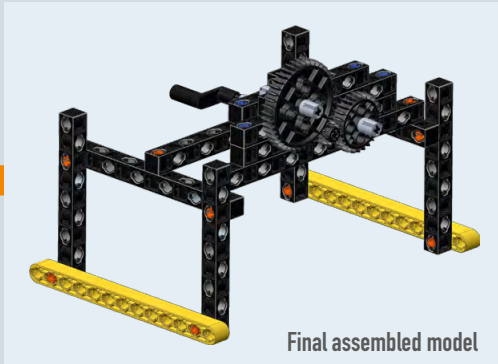


**GEAR RATIO**

Carefully observe the cogwheels when they rotate and compare the number of revolutions completed by the various cogwheels. When the larger cogwheel has completed a revolution, the smaller one will have completed 4. You can prove this by dividing the number of teeth of the two cogwheels (ratio).

Example: how to calculate the gear ratio.

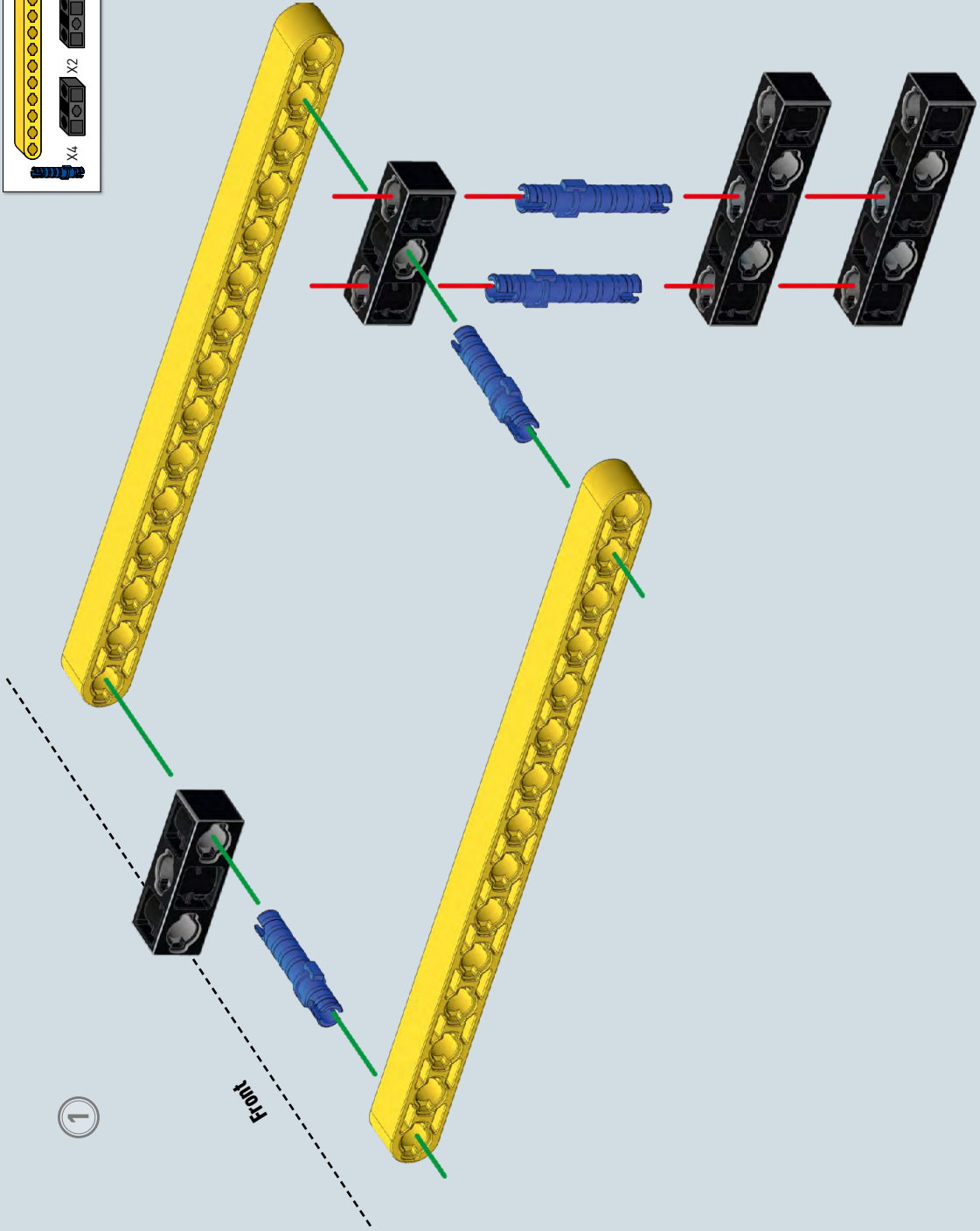
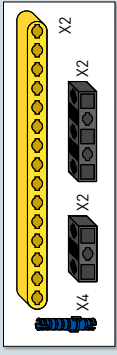
$$\frac{41 \text{ teeth (larger wheel)}}{10 \text{ teeth (smaller wheel)}} = 4.1 \text{ revolutions}$$



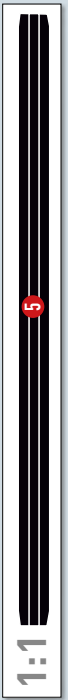
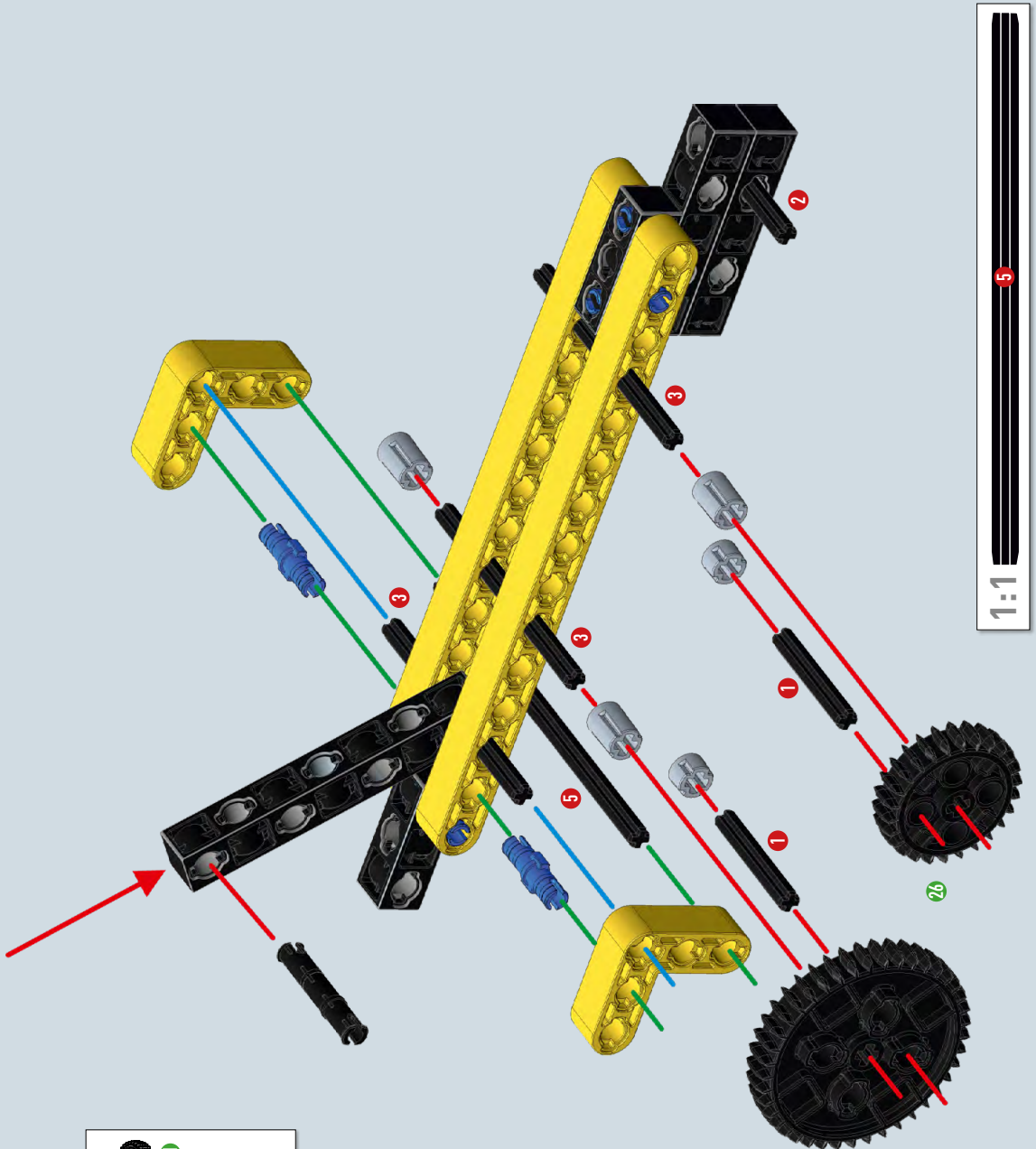
Final assembled model





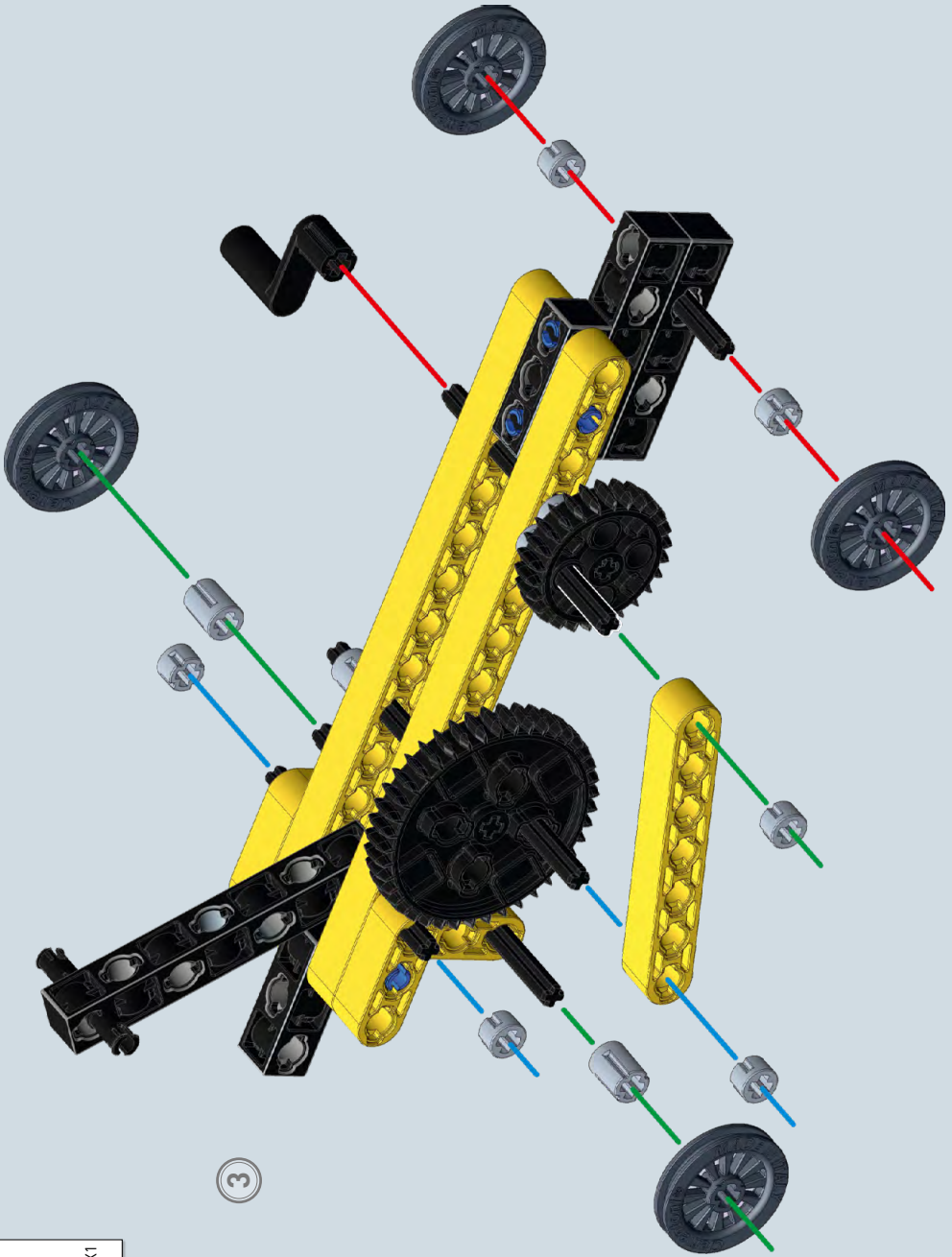






X2 X1  
 X1 X1  
 X2 X1 X2 X2 X3 X2  
 X2 X2 X3 X2  
 X1 X1

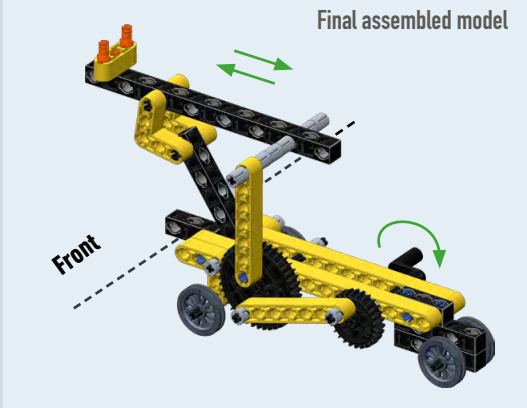
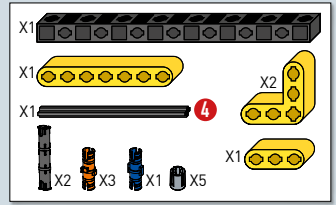
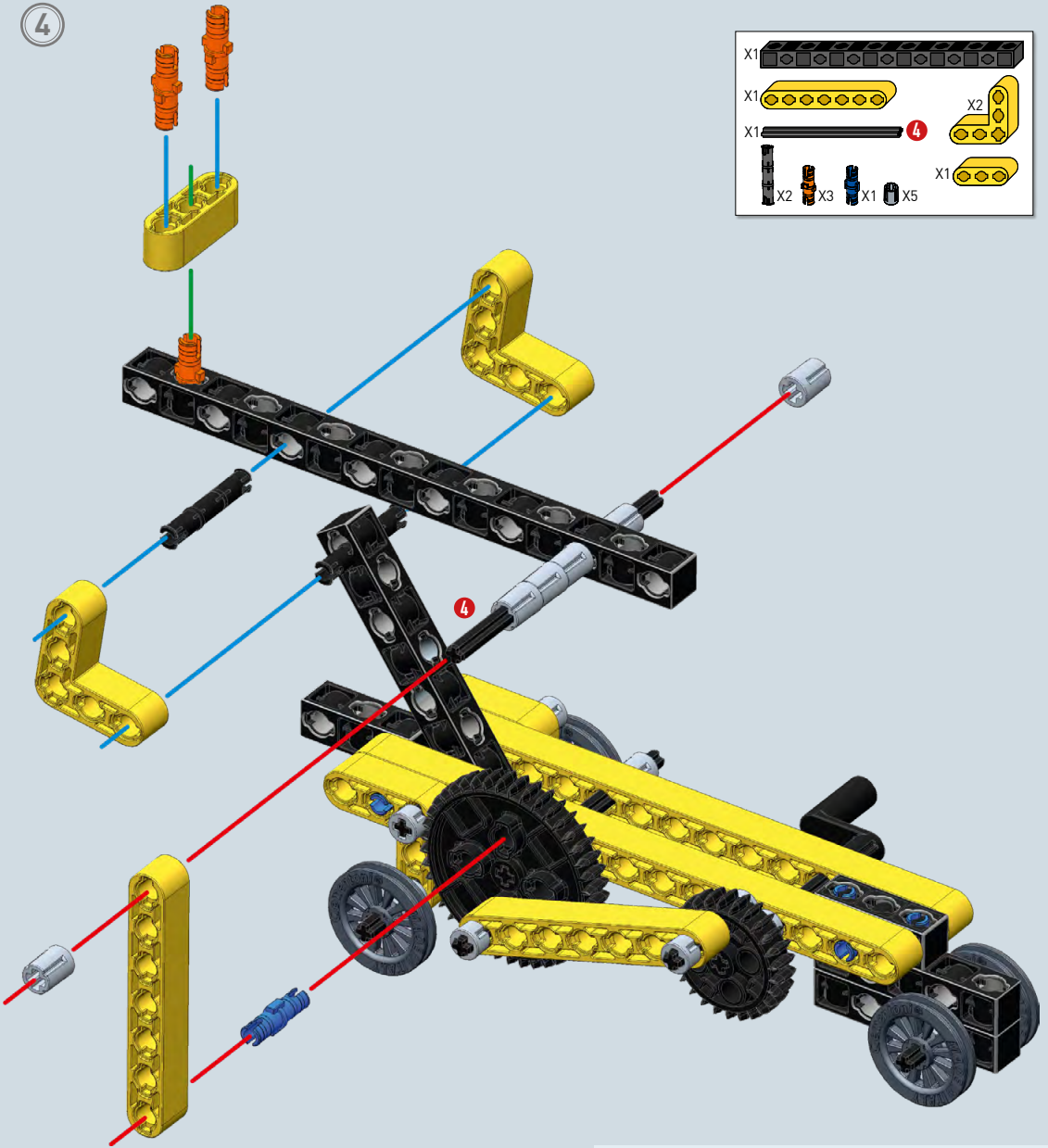
2

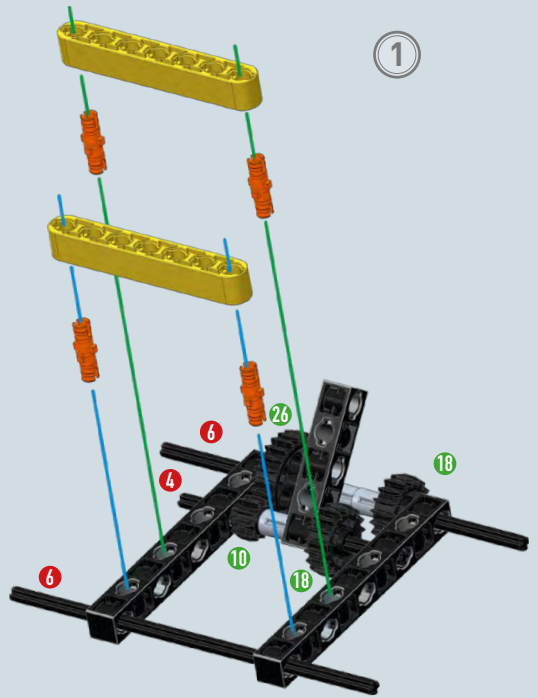
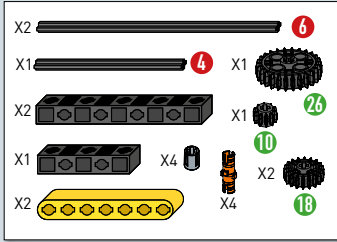


3

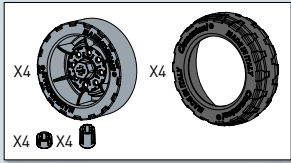
	X1		X1
	X2		
	X6		X4

4

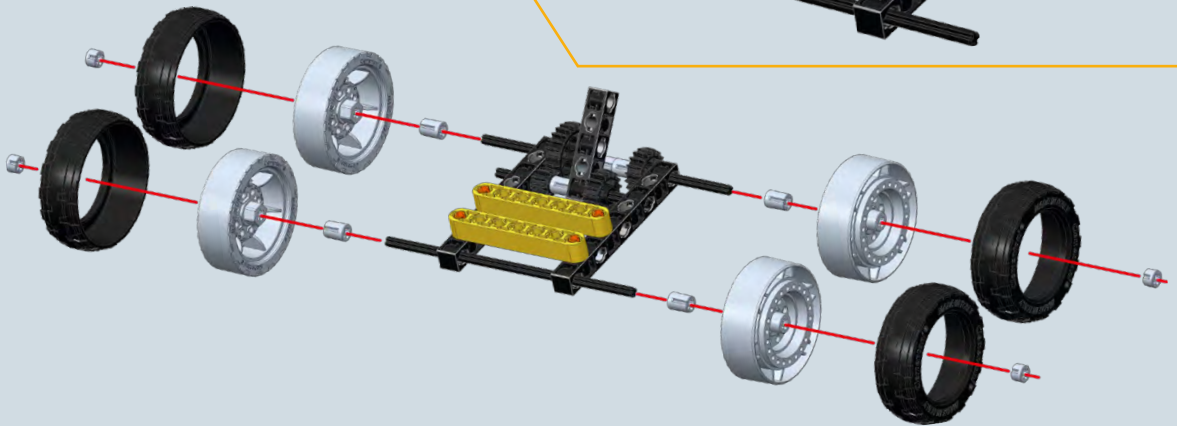




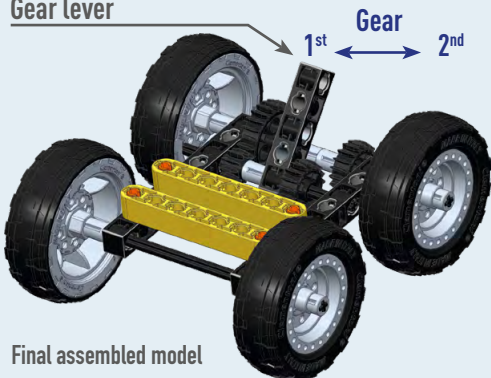
1



2



**Gear lever**



Final assembled model

**Technical facts on manual gearboxes**

In a real car the gears are sealed inside a box, called the gearbox, which is positioned between the engine axle and the wheel axles.

**Ways of changing gear**

The lever (see figure) can be used to move the various-sized cogwheels horizontally on the transmission axle to make them engage with the cogwheels on the wheel axles. Depending on the driving wheel, this causes a change in the rotation of the wheels and a change in the speed of the car.